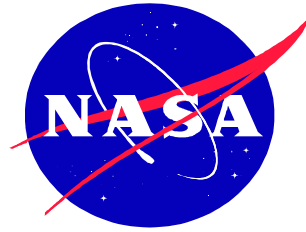




# Software Model Checking and its Tools



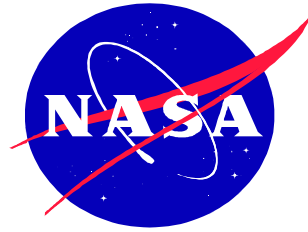
Kapitel 24, „Softwarewerkzeuge“

Courtesy to Willem Visser. Used by  
permission.

Prof. U. Aßmann, TU Dresden

Available at:

<http://www.visserhome.com/willem/presentations/presentations.html>

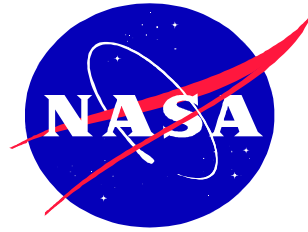


# Software Model Checking

Shortened from  
Willem Visser, Tutorial at ASE 2002

Research Institute for Advanced Computer Science  
NASA Ames Research Center

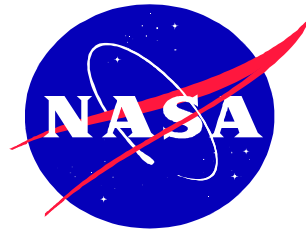
# Overview



- Introduction to Model Checking
  - Hardware and Software Model Checking
- Program Model Checking
  - Major Trends
    - Abstraction
    - Improved model checking technology
  - A Brief History
    - SPIN
    - Hand-translations
    - State-less model checking
    - Semi-automated translations
    - Fully automated translations
  - Current Trends
    - Custom-made model checkers for programs
    - SLAM
    - JPF
    - Summary
- NASA Case Studies - Remote Agent, DEOS and Mars Rover
- Future of Software Model Checking

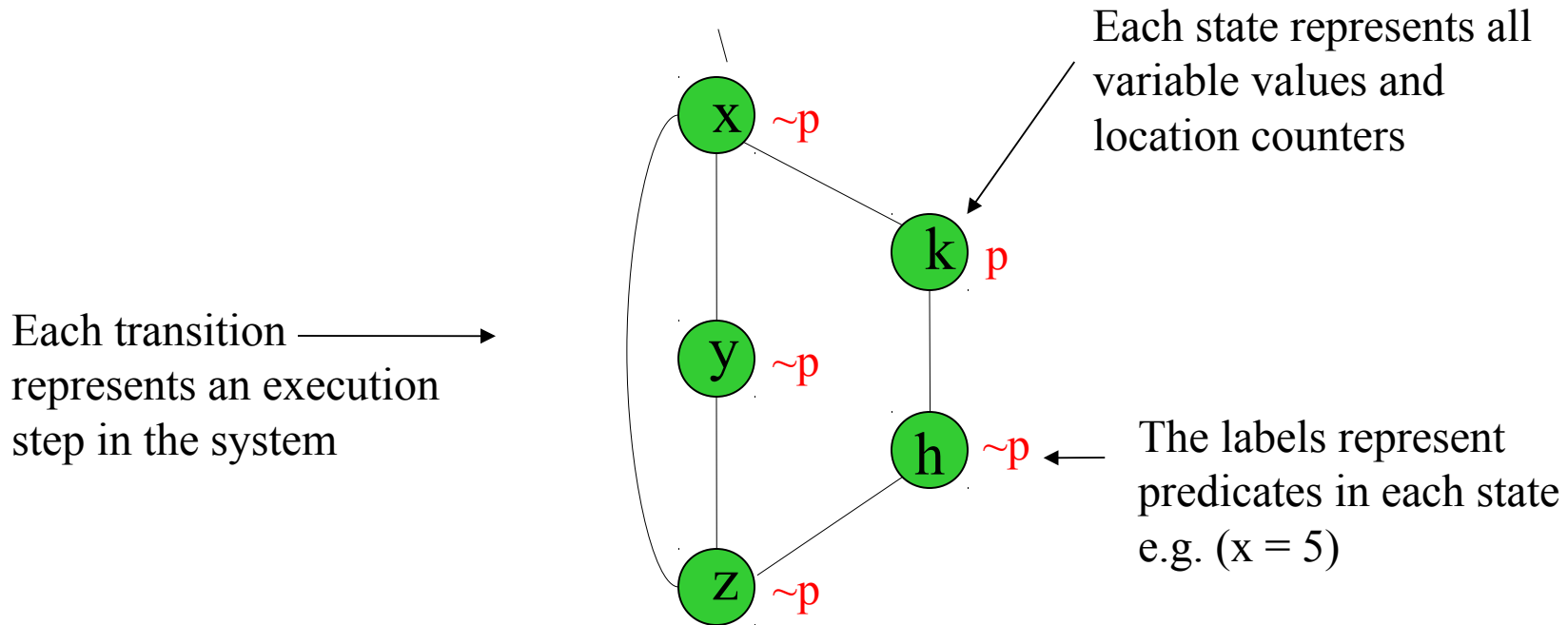
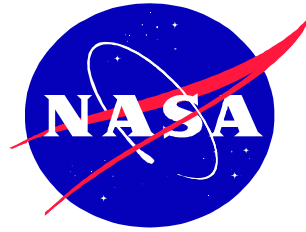
# Model Checking

## *The Intuition*



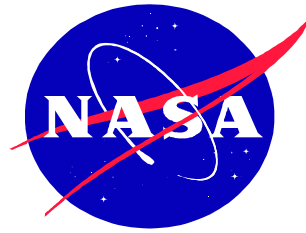
- Calculate whether a system satisfies a certain behavioral property:
  - Is the system deadlock free?
  - Whenever a packet is sent will it eventually be received?
- So it is like testing? No, major difference:
  - Look at *all* possible behaviors of a system
- Automatic, if the system is finite-state
  - Potential for being a push-button technology
  - Almost no expert knowledge required
- How do we describe the system?
- How do we express the properties?

# Kripke Structures are Labeled State Graphs plus Predicates



$$K = (\{p, \sim p\}, \{x, y, z, k, h\}, R, \{x\}, L)$$

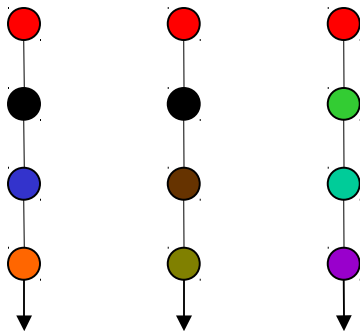
# Property Specifications with Temporal Logic



- Temporal Logic
  - Express properties of event orderings in time
  - e.g. “Always” when a packet is sent it will “Eventually” be received

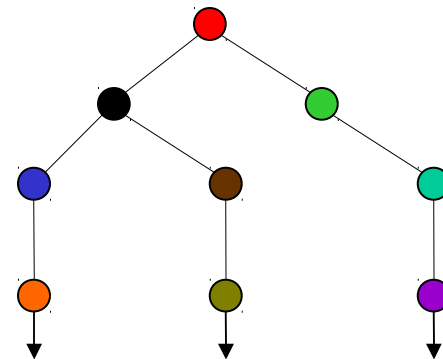
- Linear Time

- Every moment has a unique successor
- Infinite sequences (words)
- Linear Time Temporal Logic (LTL)



- Branching Time

- Every moment has several successors
- Infinite tree
- Computation Tree Logic (CTL)



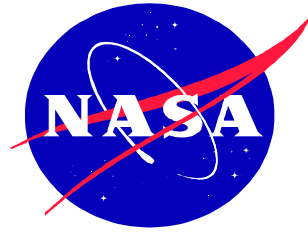
- Safety properties
  - Invariants, deadlocks, reachability, etc.
  - Can be checked on finite traces
  - “something bad never happens”
- Liveness Properties
  - Fairness, response, etc.
  - Infinite traces
  - “something good will eventually happen”

- Model checking can be done
- Forward:
  - Searching from the initial state to reachable states, checking the condition
- Backward
  - Searching from the states in which a condition should hold backward to the initial state
  - In particular possible for reachability questions





# Mutual Exclusion Example

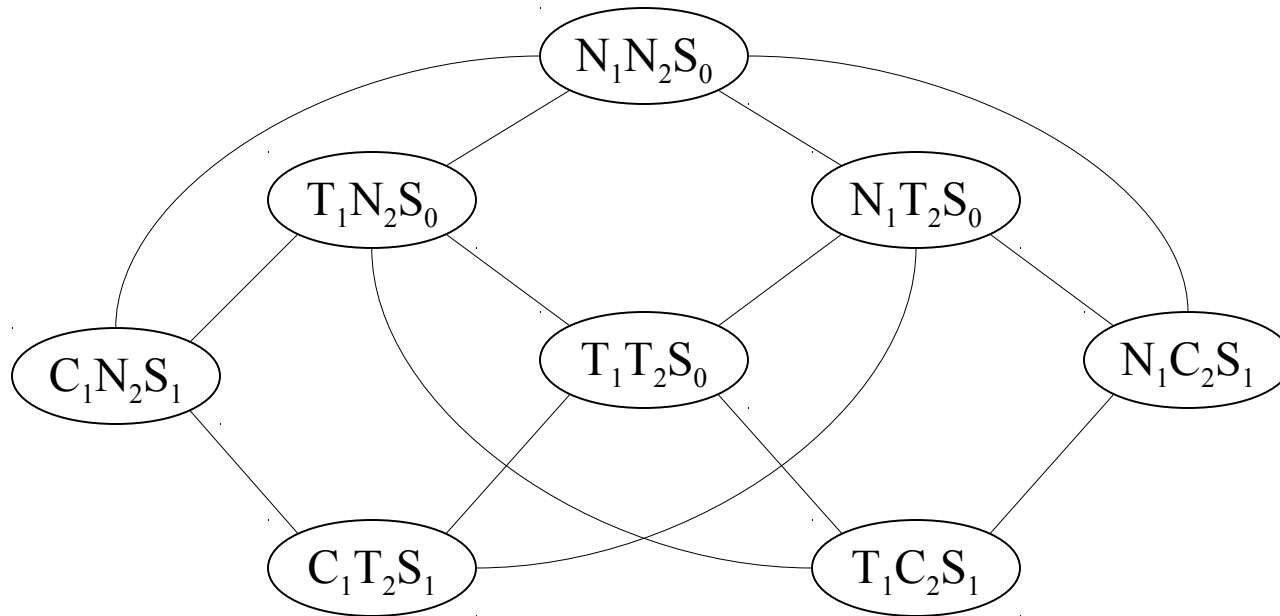


- Two process mutual exclusion with shared semaphore
- Each process has three states
  - Non-critical (N)
  - Trying (T)
  - Critical (C)
- Semaphore can be available ( $S_0$ ) or taken ( $S_1$ )
- Model checkers construct a global system state space from the process
- Initially both processes are in the Non-critical state and the semaphore is available ---  $(N_1 N_2 S_0)$

$$\begin{array}{l} N_1 \rightarrow T_1 \\ T_1 \wedge S_0 \rightarrow C_1 \wedge S_1 \\ C_1 \rightarrow N_1 \wedge S_0 \end{array} \quad || \quad \begin{array}{l} N_2 \rightarrow T_2 \\ T_2 \wedge S_0 \rightarrow C_2 \wedge S_1 \\ C_2 \rightarrow N_2 \wedge S_0 \end{array}$$

# System State Space

## (Backward Reachability Question)



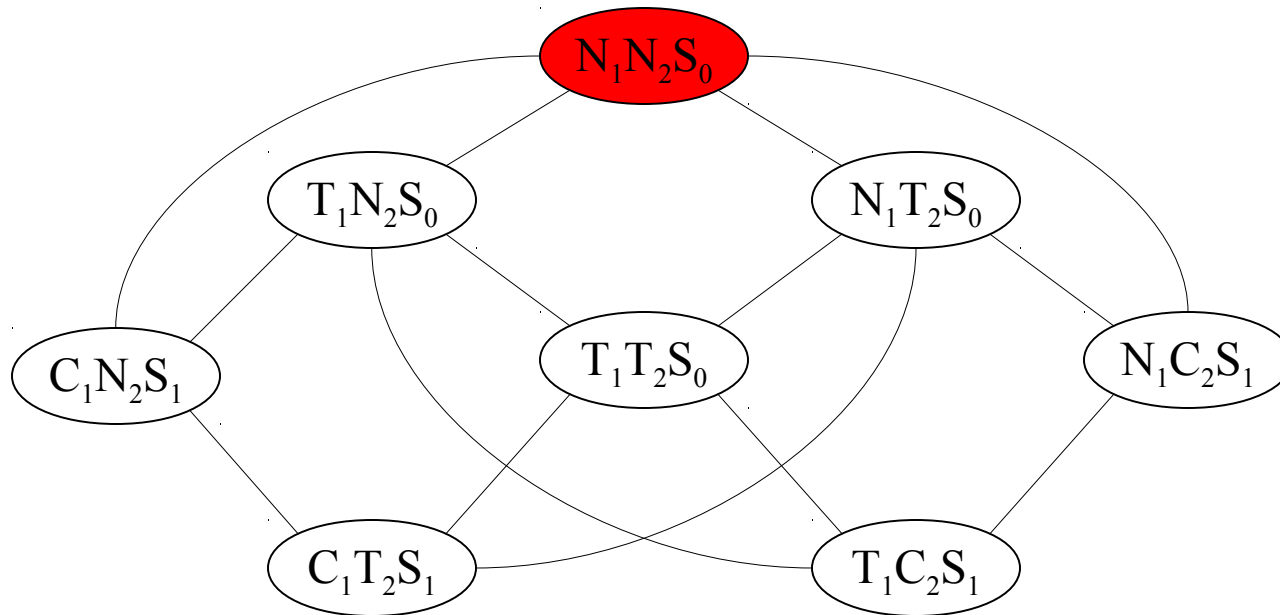
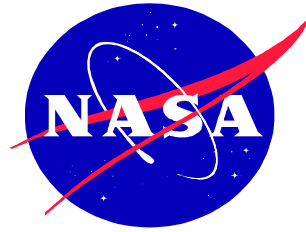
$$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$$

*All Globally*

*No matter where you are there is always a way to get to the initial state*

*Exist Finally*

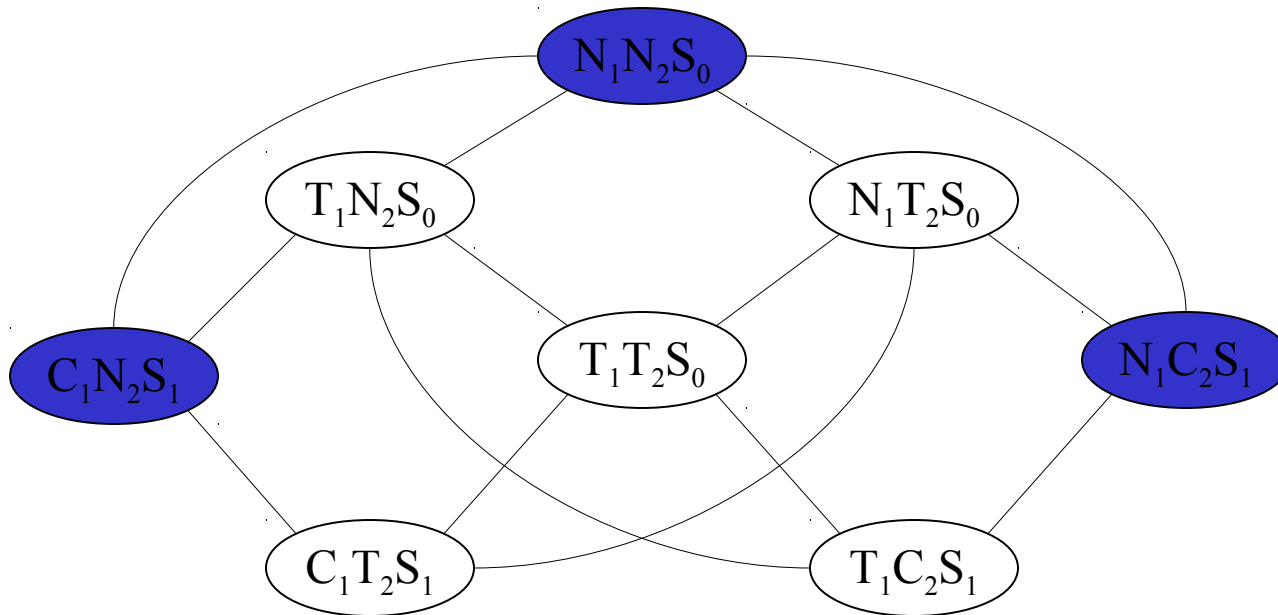
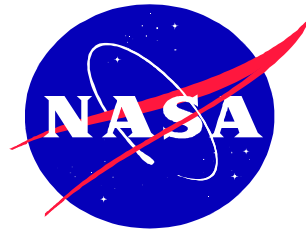
# Mutual Exclusion Example: Backward Analysis



$$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$$

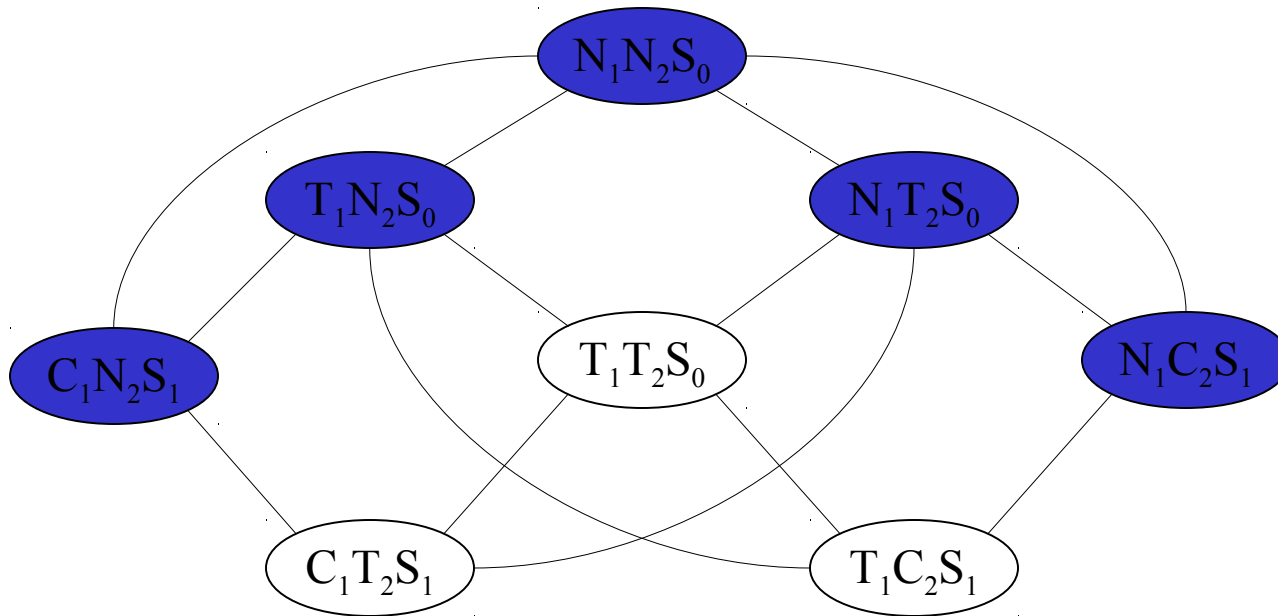
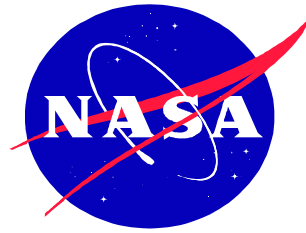
Model checkers do reachability of states: here, backward  
Search for paths.

# Mutual Exclusion Example



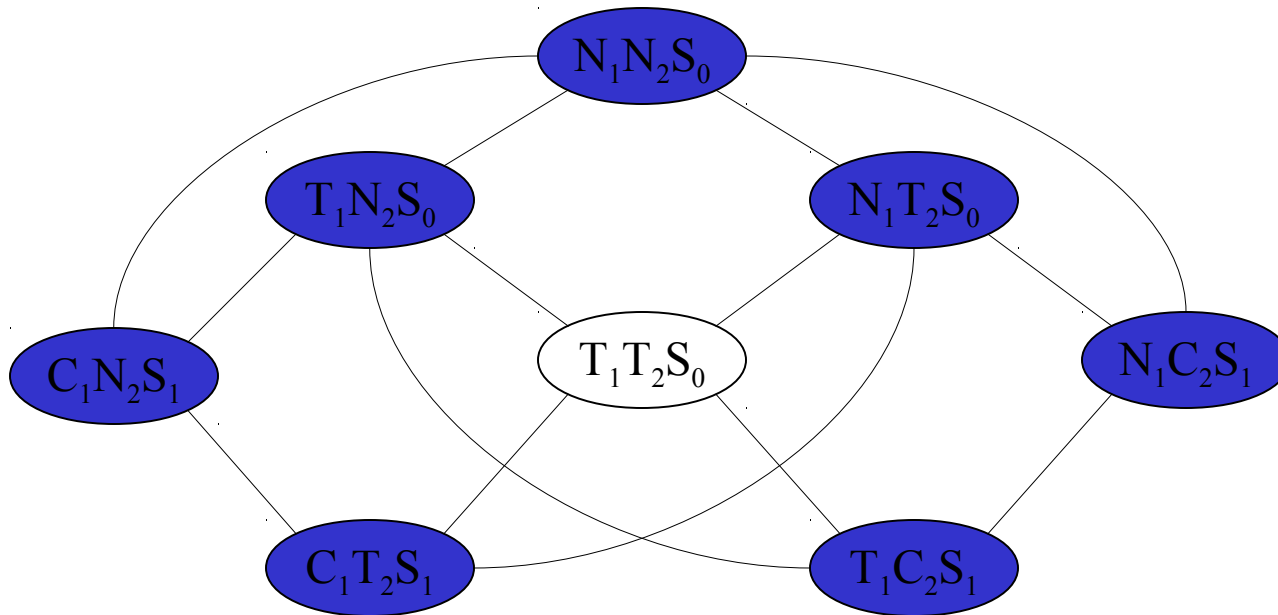
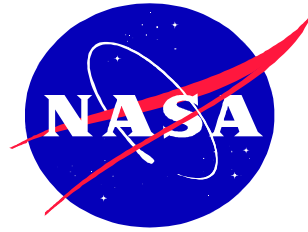
$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$

# Mutual Exclusion Example



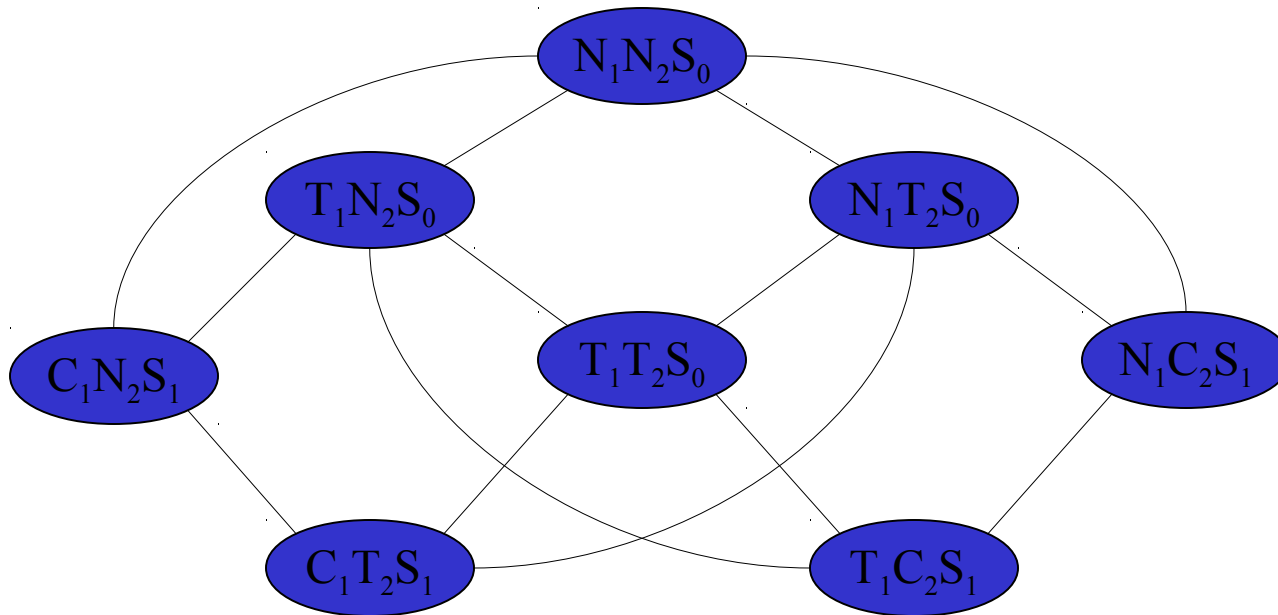
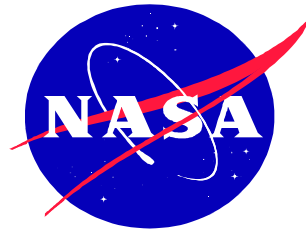
$$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$$

# Mutual Exclusion Example



$$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$$

# Mutual Exclusion Example



$$K \models \text{AG EF } (N_1 \text{ and } N_2 \text{ and } S_0)$$

Proven.

# Model Checking

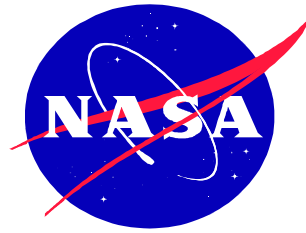
- Given a Kripke structure  $M = (S, R, L)$  that represents a finite-state concurrent system and a temporal logic formula  $f$  expressing some desired specification, find the set of states in  $S$  that satisfy  $f$ :

$$\{ s \text{ in } S \mid M, s \models f \}$$

- Normally, some states of the concurrent system are designated as initial states. The system satisfies the specification provided all the initial states are in the set. We often write:  $M \models f$

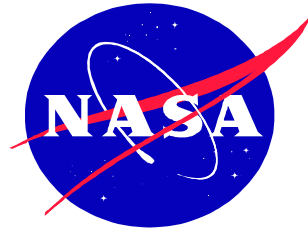


# Explicit vs. Symbolic Model Checking



- Explicit State
  - states are enumerated on-the-fly
  - *Forwards* analysis
  - Stores visited states in a hashtable
- Characteristics
  - Memory intensive
  - Good for finding concurrency errors
  - Short execution paths are better, but long execution paths can also be handled
  - Can handle dynamic creation of objects/threads
  - Mostly used in software
- Symbolic
  - **Sets of states** are manipulated at a time
  - Typically a *backwards* analysis in the automaton
  - Transition relation encoded by Binary Decision Diagrams (BDDs) or as a satisfiability problem
- Characteristics
  - Can handle very large state spaces
  - Not as good for asynchronous systems
  - Cannot deal well with long execution traces
  - Works best with a static transition relation, hence doesn't deal well with dynamic creation of objects/threads
  - Mostly used in hardware

# Overview



- Introduction to Model Checking
  - Hardware Model Checking
  - Software Model Checking
- Program Model Checking
- Case Studies
- Future of Software Model Checking

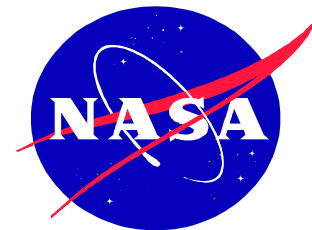
- BDD-based model checking was the enabling technology
  - Hardware is typically synchronous and regular, hence the transition relation can be encoded efficiently
  - Execution paths are typically very short
- The Intel Pentium bug
  - got model checking on the map in the hardware industry
  - Intel, IBM, Motorola, etc. now employ hundreds of model checking experts

- Until 1997 most work was on software designs
  - Since catching bugs early is more cost-effective
  - Problem is that everybody use a different design notation, and although bugs were found the field never really moved beyond some compelling case-studies
  - Reality is that people write code first, rather than design
- The field took off when the seemingly harder problem of analyzing actual source code was first attempted

- Why is program analysis with a model checker so much more interesting?
  - Designs are hard to come by, but buggy programs are everywhere!
  - Testing is inadequate for complex software (concurrency, pointers, objects, etc.)
  - Static program analysis was already an established field, mostly in compiler optimization, but also in verification.

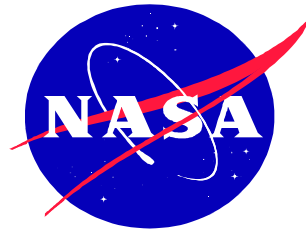


# The Trends in Program Model Checking



*Most model checkers cannot deal with the features of  
modern programming languages*

- Bringing programs to model checking
  - By abstraction (including translation)
- Bringing model checking to programs
  - Improve model checking to directly deal with programs as input



- Introduction to Model Checking
- Program Model Checking
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# Program (Software) Model Checking

Abstraction of the Control-Flow Graph  
from Stack Automaton to Finite Automaton

## Program

```

void add(Object o) {
    buffer[head] = o;
    head = (head+1)%size;
}

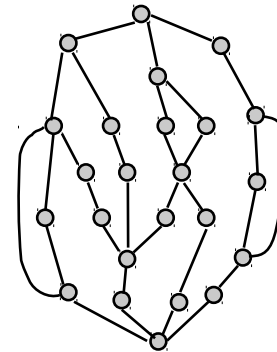
Object take() {
    ...
    tail=(tail+1)%size;
    return buffer[tail];
}
    
```

Infinite state



## Model Checker

### Input



Finite state

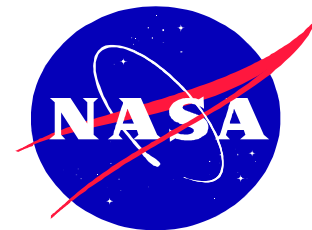


# Abstraction

- Model checkers don't take real "programs" as input
- Model checkers typically work on finite state systems
- Abstraction therefore solves two problems
  - It allows model checkers to analyze a notation they couldn't deal with before, and,
  - Cuts the state space size to something manageable
- Abstraction comes in three flavors
  - **Over-approximations**, i.e. *more behaviors* are added to the abstracted system than are present in the original
  - **Under-approximations**, i.e. *less behaviors* are present in the abstracted system than are present in the original
  - **Precise abstractions**, i.e. *the same behaviors* are present in the abstracted and original program

# Under-Approximation

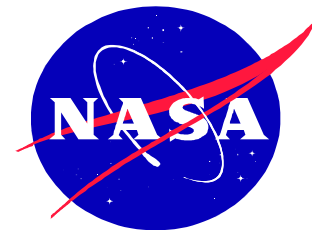
## *“Meat-Axe” Abstraction*



- Remove parts of the program deemed “irrelevant” to the property being checked
  - Limit input values to 0..10 rather than all integer values
  - Queue size 3 instead of unbounded, etc.
- Typically manual, with no guarantee that the right behaviors are removed
- Precise abstraction, w.r.t. the property being checked, may be obtained if the behaviors being removed are indeed not influencing the property
  - Program *slicing* is an example of an automated under-approximation that will lead to a precise abstraction w.r.t. the property being checked
  - However, can be incorrect

# Over-Approximations

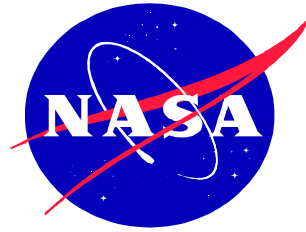
## *Abstract Interpretation*



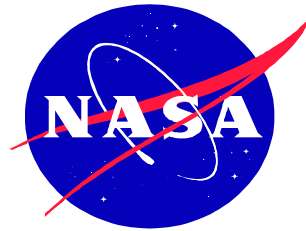
- Over-Approximation maps sets of states in the concrete program to one state in the *abstract program (Abstract Interpretation)*
  - Reduces the number of states, but increases the number of possible transitions, and hence the number of behaviors
- Type-based abstractions
  - Replace int by Signs abstraction {neg,pos,zero}
- Predicate abstraction
  - Replace predicates in the program by boolean variables, and replace each instruction that modifies the predicate with a corresponding instruction that modifies the boolean.
- Automated (conservative) abstraction: correct
- Eliminating spurious errors is the big problem
  - Abstract program has more behaviors, therefore when an error is found in the abstract program, is that also an error in the original program?
  - Most research focuses on this problem, and its counter-part the elimination of spurious errors, often called *abstraction refinement*



# Bringing Model Checking to Programs



- Allow model checkers to take modern programming languages as input
  - Major hurdle is how to encode the state of the system efficiently
  - Alternatively state-less model checking
    - No state encoding or storing
- Almost exclusively explicit-state model checking
- Abstraction can still be used as well
  - Source to source abstractions



- Introduction to Model Checking
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    - SPIN
    - Hand-translations
    - State-less model checking
      - Partial-order reductions
      - VeriSoft
    - Semi-automated translations
    - Fully automated translations
  - Current Trends
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# The Early Years

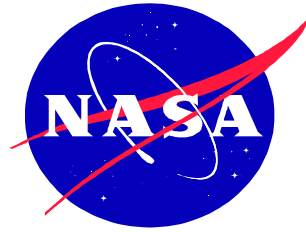
- Hand-translation with ad-hoc abstractions
  - 1980 through mid 1990s
- Semi-automated, table-driven translations
  - 1998
- Automated translations still with ad-hoc abstractions
  - 1997-1999
- State-less model checking for C
  - VeriSoft 1997

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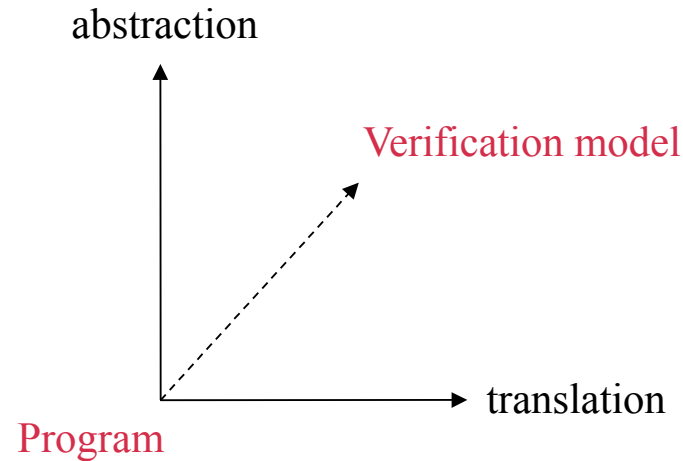


# SPIN Model Checker



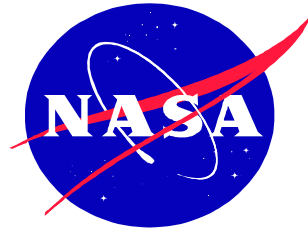
- Kripke structures are described as “programs” in the PROMELA language
  - Kripke structure is generated on-the-fly during model checking
- Automata based model checker
  - Translates LTL formula to Büchi automaton
- By far the most popular model checker
  - SPIN workshop
- Relevant theoretical papers can be found here
  - <http://netlib.bell-labs.com/netlib/spin/whatispin.html>
- Ideal for software model checking due to expressiveness of the PROMELA language
  - Close to a real programming language
- Gerard Holzmann won the ACM software award for SPIN



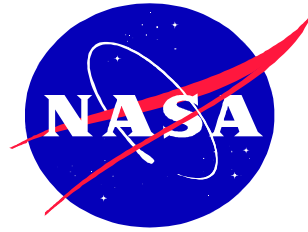


- Hand translation of program to model checker's input notation
- “Meat-axe” approach to abstraction (under-approximation)
- Labor intensive and error-prone

# Hand-Translation Examples

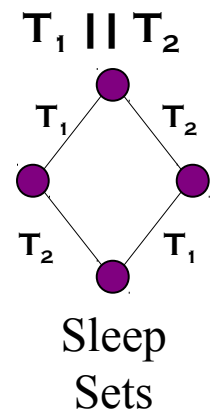
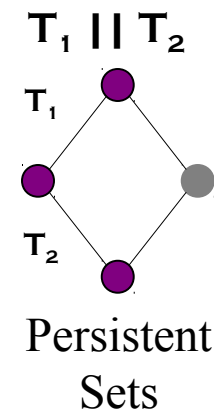
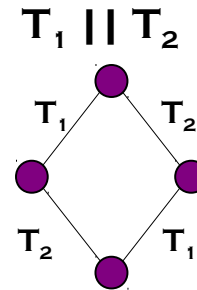


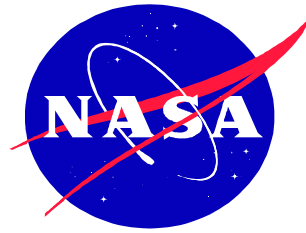
- Remote Agent – Havelund, Penix, Lowry 1997
  - <http://ase.arc.nasa.gov/havelund>
  - Translation from Lisp to Promela (most effort)
  - Heavy abstraction
  - 3 man months
- DEOS operating system – Penix, Visser, *et al.* 1998/1999
  - <http://ase.arc.nasa.gov/visser>
  - C++ to Promela (most effort in environment generation)
  - Limited abstraction - programmers produced sliced system
  - 3 man months



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- The first model checker that could handle programs directly
  - C programs running on Unix
- Relies on partial-order reductions to limit the number of times a state is revisited
  - Persistent sets
    - Reduce states visited
  - Sleep sets
    - Reduce transitions executed
- Paths must be replayed from the initial state to try new branches
  - No check-pointing

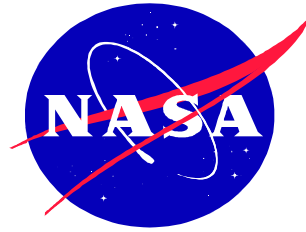




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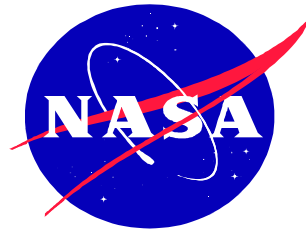
# Semi-Automatic Translation



- Table-driven translation and abstraction
  - Feaver system by Gerard Holzmann
  - User specifies code fragments in C and how to translate them to Promela (SPIN)
  - Translation is then automatic
  - Found 75 errors in Lucent's PathStar system
  - <http://cm.bell-labs.com/cm/cs/who/gerard/>
- Advantages
  - Can be reused when program changes
  - Works well for programs with long development and only local changes

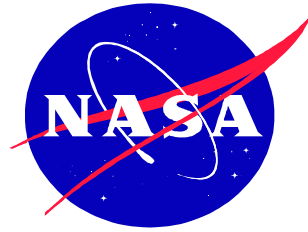


# Fully Automatic Translation



- Advantage
  - No human intervention required
- Disadvantage
  - Limited by capabilities of target system
- Examples
  - Java PathFinder 1- <http://ase.arc.nasa.gov/havelund/jpf.html>
    - Translates from Java to Promela (Spin)
  - JCAT - <http://www.dai-arc.polito.it/dai-arc/auto/tools/tool6.shtml>
    - Translates from Java to Promela (or dSpin)
  - Bandera - <http://www.cis.ksu.edu/santos/bandera/>
    - Translates from Java bytecode to Promela, SMV or dSpin

# Overview

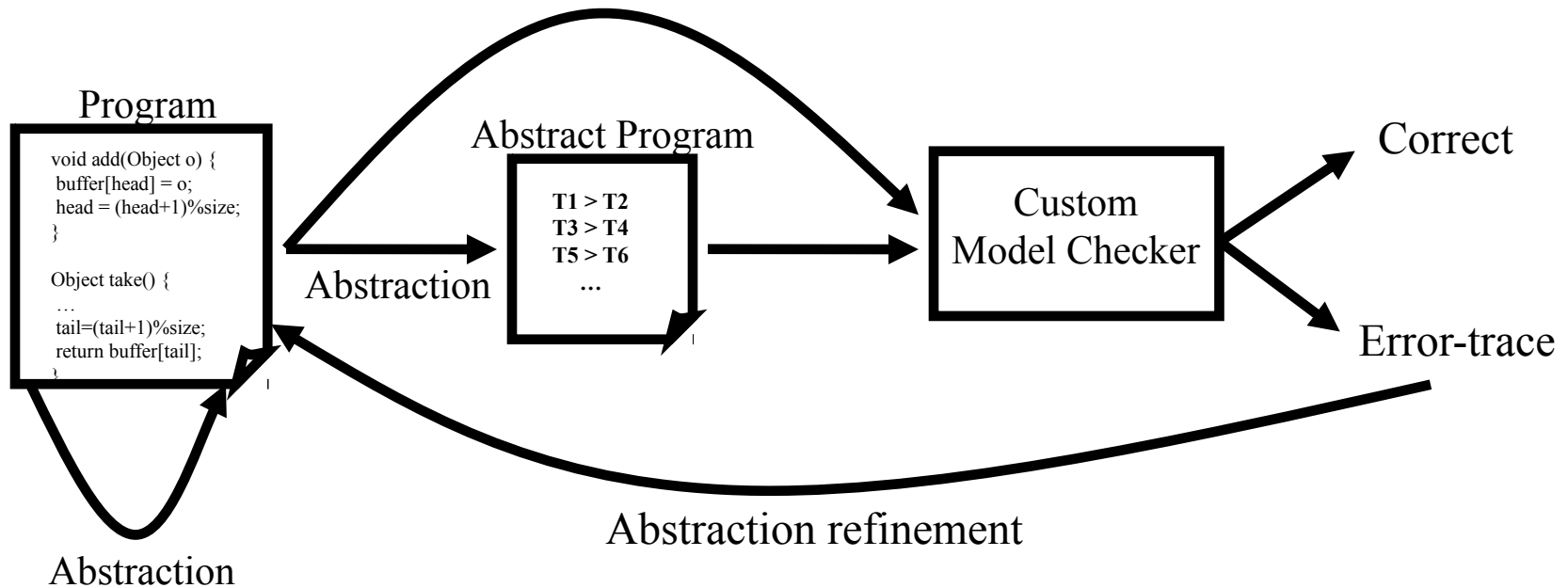
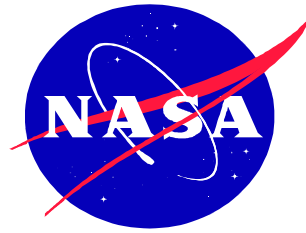


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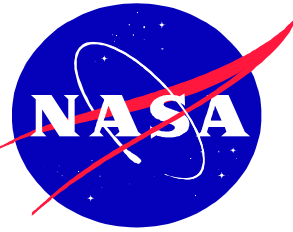


# Program Model Checking

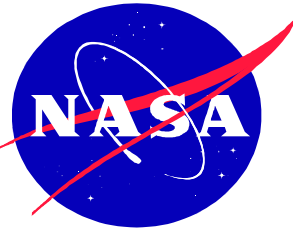
## Current Trends



- Custom-made model checkers for programming languages with automatic abstraction at the source code level
- Automatic abstraction & translation based transformation to new “abstract” formalism for model checker
- Abstraction refinement mostly automated

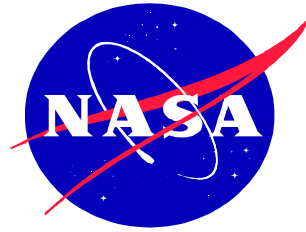


- Translation based
  - dSpin
    - Spin extended with dynamic constructs
    - Essentially a C model checker
    - Source-2-source abstractions can be supported
    - <http://www.dai-arc.polito.it/dai-arc/auto/tools/tool7.shtml>
  - SPIN Version 4
    - PROMELA language augmented with C code
    - Table-driven abstractions
  - Bandera
    - Translated Bandera Intermediate Language (BIR) to a number of back-end model checkers, but, a new BIR custom-made model checker is under development
    - Supports source-2-source abstractions as well as property-specific slicing
    - <http://www.cis.ksu.edu/santos/bandera/>



- Abstraction based
  - SLAM
    - C programs are abstracted via predicate abstraction to boolean programs for model checking
    - <http://research.microsoft.com/slam/>
  - BLAST
    - Similar basic idea to SLAM, but using *lazy* abstraction, i.e. during abstraction refinement don't abstract the whole program only certain parts
    - <http://www-cad.eecs.berkeley.edu/~tah/blast/>
  - 3-Valued Model Checker (3VMC) extension of TVLA for Java programs
    - <http://www.cs.tau.ac.il/~yahave/3vmc.htm>
    - <http://www.math.tau.ac.il/~rumster/TVLA/>

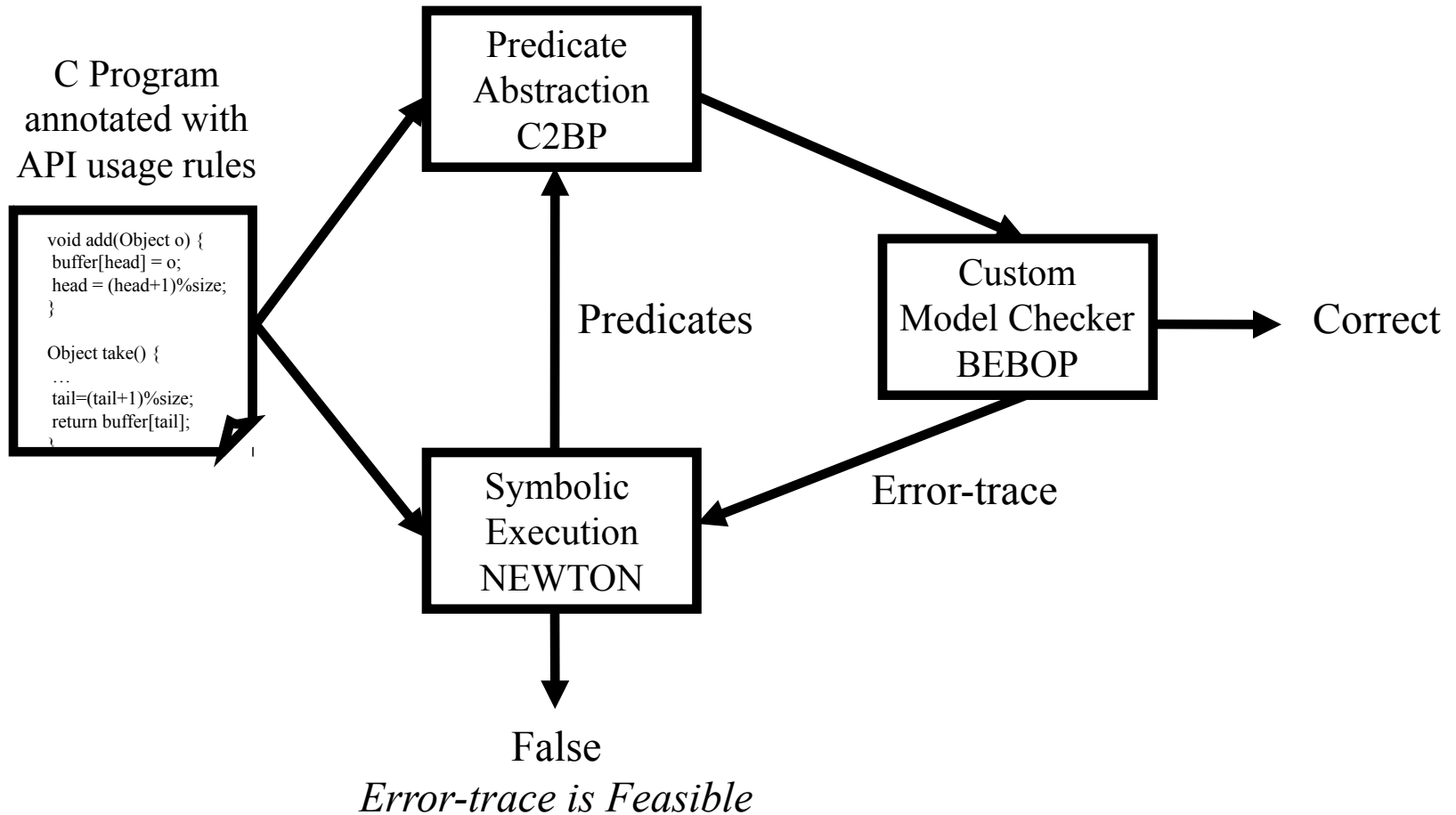
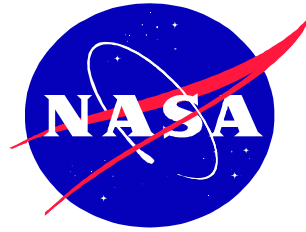
# Overview



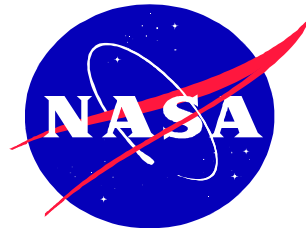
- Introduction to Model Checking
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# SLAM

## *Simplified View*



- Check API usage rules for sequential C programs
  - Mostly applied to device driver code
- C2BP
  - Inputs: C program and predicates
  - Output: boolean program over the predicates
- BEBOP
  - Symbolic interprocedural data flow analysis
  - Concrete CFG and BDD encoding of states
- NEWTON
  - Symbolic execution of C programs
  - Using Simplify theorem prover for checking feasibility of conditionals



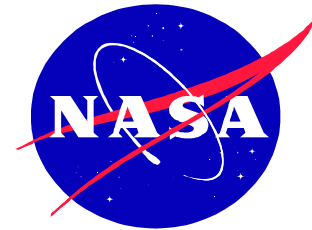
Property: *if a lock is held it must be released before reacquiring*

```
do {
    //get the write lock
    KeAcquireSpinLock (&devExt->writeListLock);

    nPacketsOld = nPackets;
    request = devExt->WLHeadVa;

    if (request){
        KeReleaseSpinLock (&devExt->writeListLock);
        ...
        nPackets++;
    }
} while (nPackets != nPacketsOld);
KeReleaseSpinLock (&devExt->writeListLock);
```

# Initial Abstraction and Model Checking



## Boolean Program (simpler, abstracted)

```
[1] do
    //get the write lock
[2]     AcquireLock();
[3]     if (*) then
[4]         ReleaseLock();
        fi
[5] while (*);
[6] ReleaseLock();
```

**Error-trace : 1,2,3,5,1,2**



# Symbolic Execution

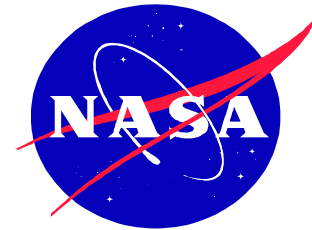
```

[1] do {
[2]     KeAcquireSpinLock (&devExt->writeListLock) ;
        nPacketsOld = nPackets;
        request = devExt->WLHeadVa;
[3]     if (request){
[4]         KeReleaseSpinLock (&devExt->writeListLock) ;
            ...
            nPackets++;
        }
[5] } while (nPackets != nPacketsOld) ;
[6] KeReleaseSpinLock (&devExt->writeListLock) ;

```

Symbolic execution of 1,2,3,5,1,2 shows that when 5 is executed `nPackets == nPacketsOld` hence the path is infeasible. The predicate `nPackets == nPacketsOld` is then added and used during predicate abstraction

# Next Abstraction and Model Checking



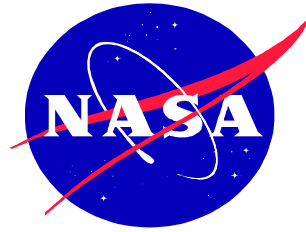
**New Predicate  $b$  : (nPacketsOld == nPackets)**

```

[1] do
[2]   AcquireLock ();
[3]   b = true; // nPacketsOld = nPackets
[4]   if (*) then
[5]     ReleaseLock ();
[6]     b = b ? false : *; // nPackets++
      fi
[7] while (!b); // (nPacketsOld != nPackets)
[8] ReleaseLock ();

```

**Now property holds**

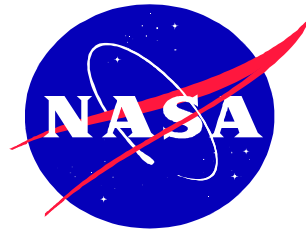


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      - Partial-order and symmetry reductions
      - Heuristics
      - New Stuff
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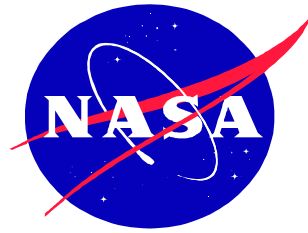
# Java PathFinder (2)

## Direct Approach



- Based on custom-made Java Virtual Machine
  - Handle all of Java, since it works with bytecodes
  - Written in Java
- Efficient encoding of states
- Modular design for easy extensions
- Supports LTL checking with properties expressed in Bandera's BSL notation
- Incorporates a number of search strategies
  - DFS, BFS, A\*, Best-first, etc.
- Supports source-2-source abstractions
- <http://ase.arc.nasa.gov/jpf>

# Java PathFinder (JPF)



## Java Code

```
void add(Object o) {
    buffer[head] = o;
    head = (head+1)%size;
}

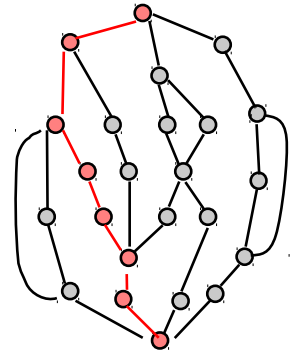
Object take() {
    ...
    tail=(tail+1)%size;
    return buffer[tail];
}
```

JAVAC

## Bytecode

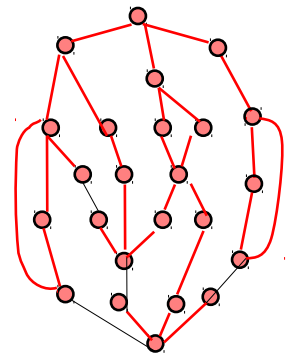
```
0:   iconst_0
1:   istore_2
2:   goto   #39
5:   getstatic
8:   aload_0
9:   iload_2
10:  aaload
```

JVM

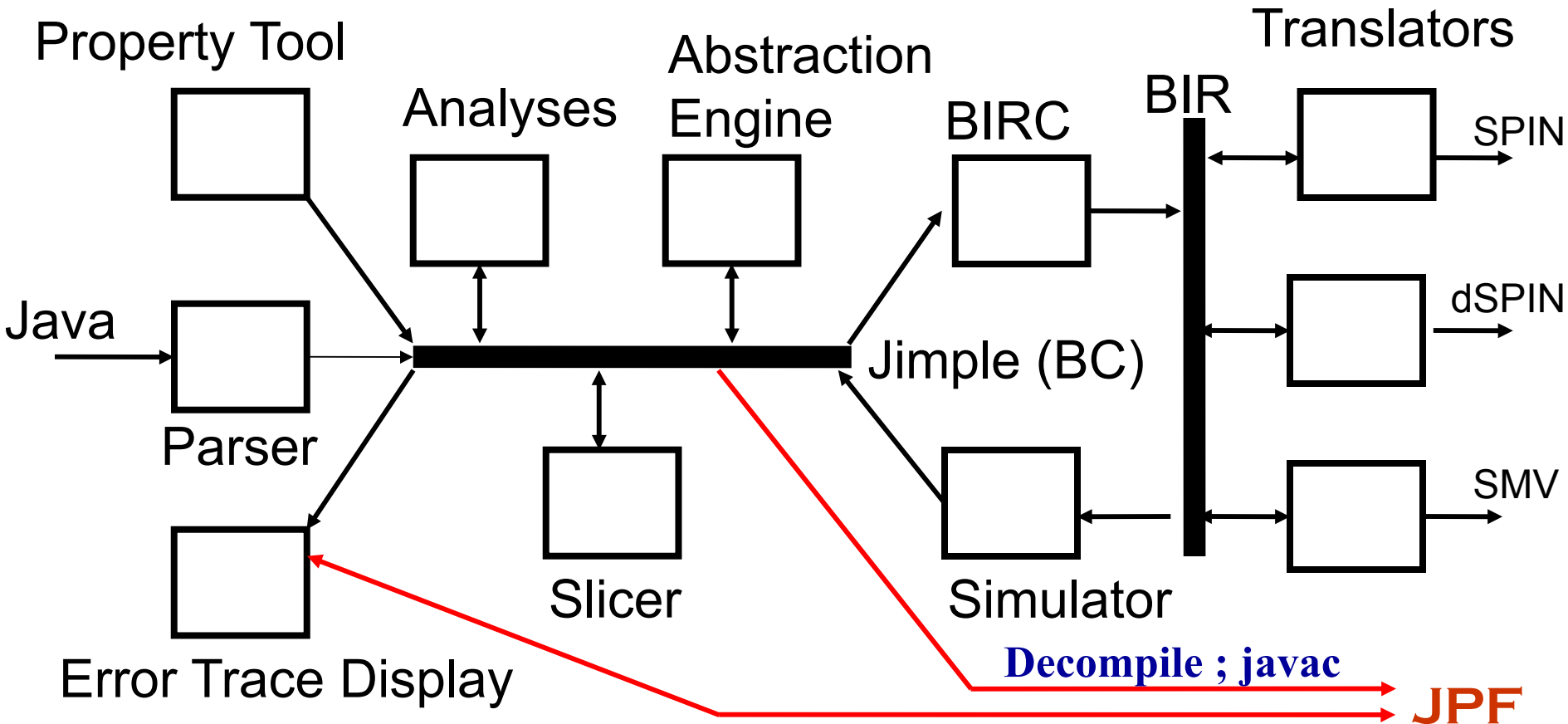
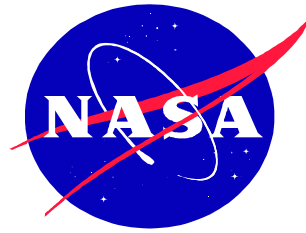


Model  
Checker

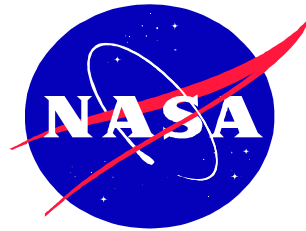
Special  
JVM



# Bandera & JPF Architecture

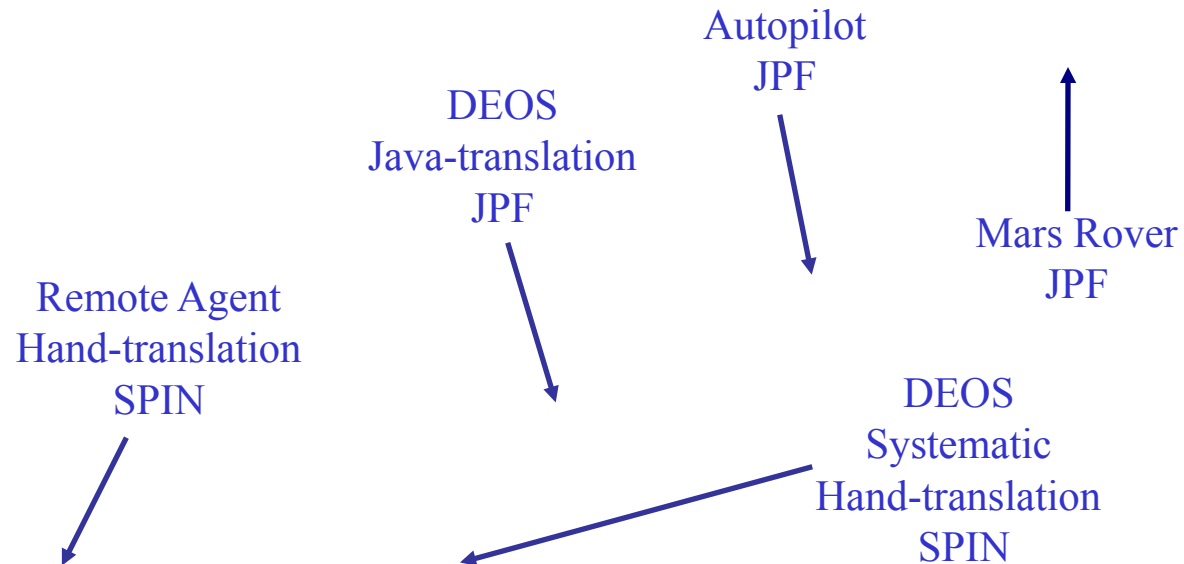
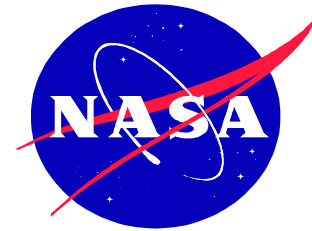


# Key Points



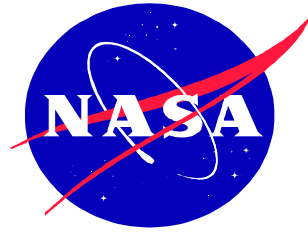
- Models can be infinite state
  - Unbounded objects, threads,...
  - Depth-first state generation (explicit-state)
  - Verification requires abstraction
- Handle full Java language
  - but only for closed systems
  - Cannot handle native code
    - no Input/output through GUIs, files, Networks, ...
    - Must be modeled by java code instead
- Allows Nondeterministic Environments
  - JPF traps special nondeterministic methods
- Checks for User-defined assertions, deadlock and LTL properties

# Scaling Program Model Checking Error-Detection





# Overview

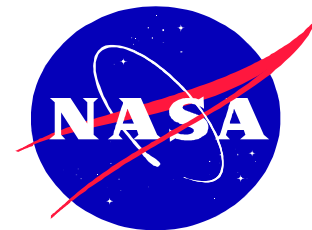


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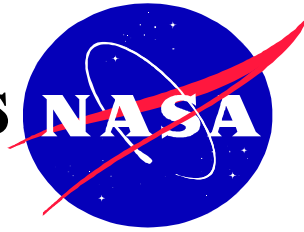


# Software Model Checking

## Executive summary

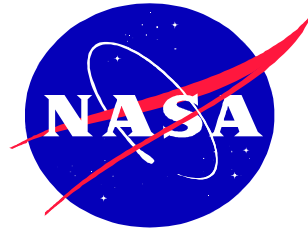


- Model checking by itself cannot deal with the complexity of software
- Techniques from static analysis are required
  - Abstract interpretation, slicing, alias&shape analysis, symbolic execution
- Even then, we need to borrow some more!
  - Heuristic search, constraint solving, etc.
- Abandon soundness
  - Aggressive heuristics
  - Runtime analysis and runtime monitoring



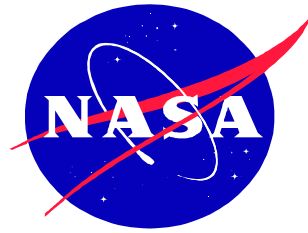
## *A small sample*

- Program Verification
  - For example, ESC/Java from Compaq
    - <http://research.compaq.com/SRC/esc/>
- Static analysis for runtime errors
  - For example, PolySpace for C, Ada and Java
    - <http://www.polyspace.com/>
- Requirements and Design Analysis
  - Analysis for SCR, RSML, Statecharts, etc.
- Runtime analysis
  - See Runtime Verification Workshops
    - <http://ase.arc.nasa.gov/rv2002/>
- Analysis Toolsets
  - IF (Verimag), SAL (SRI), etc.

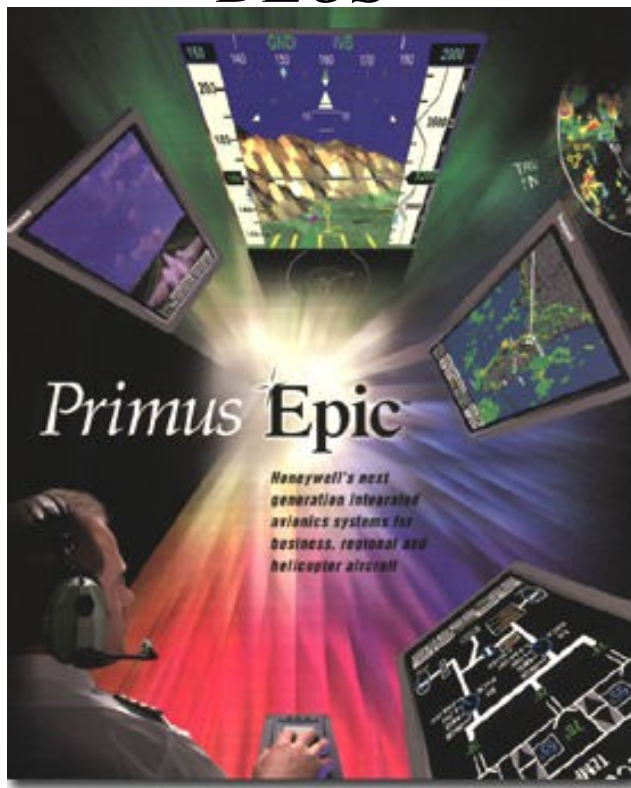


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- Case Studies
  - Remote Agent
  - DEOS
  - Mars Rover
- Future of Software Model Checking

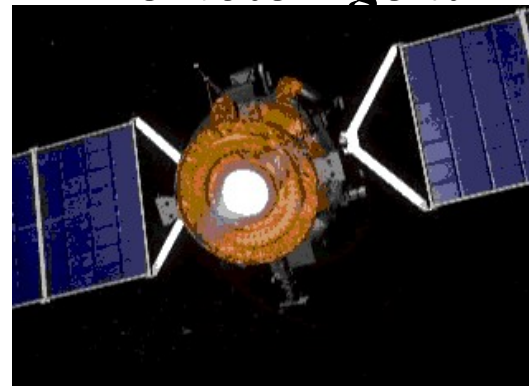
# Case Studies of JPF



*DEOS*



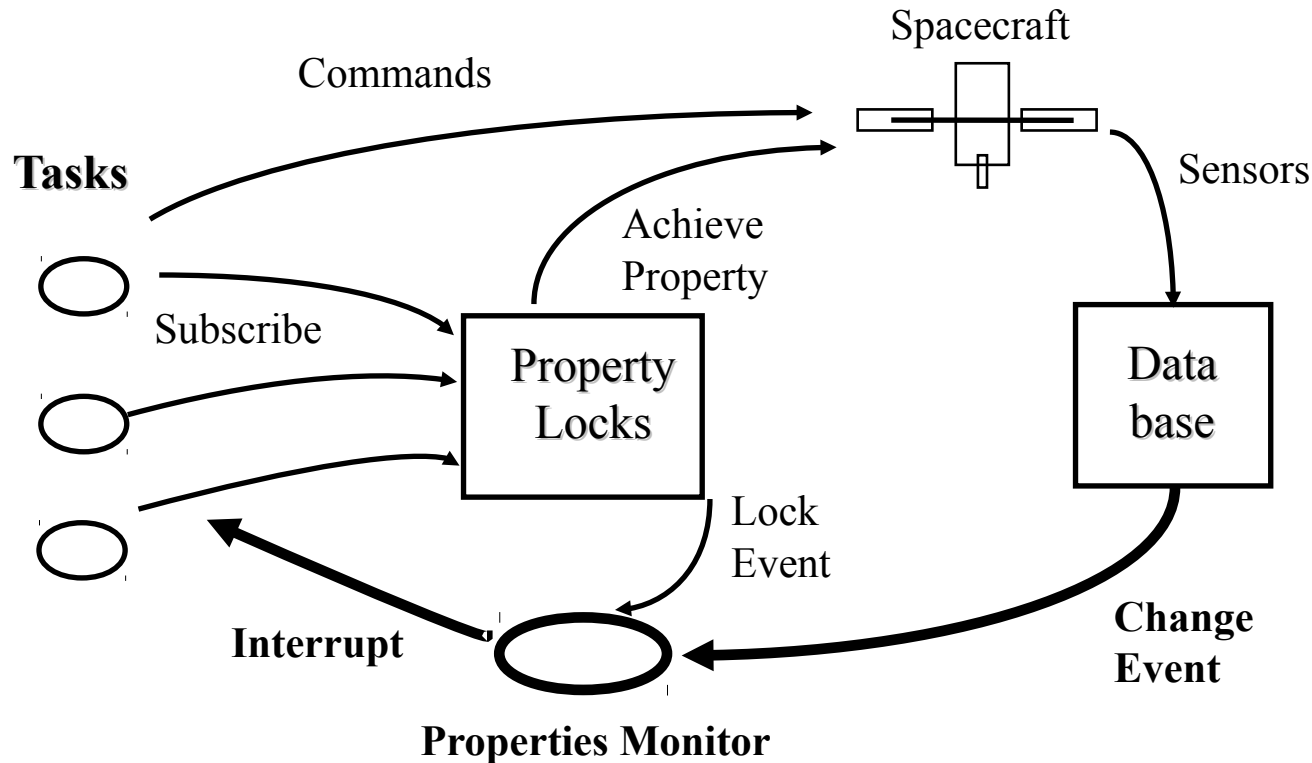
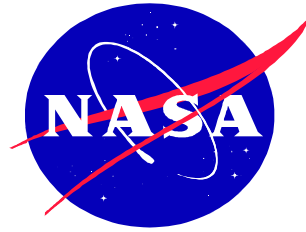
*Remote Agent*



*Mars Rover*

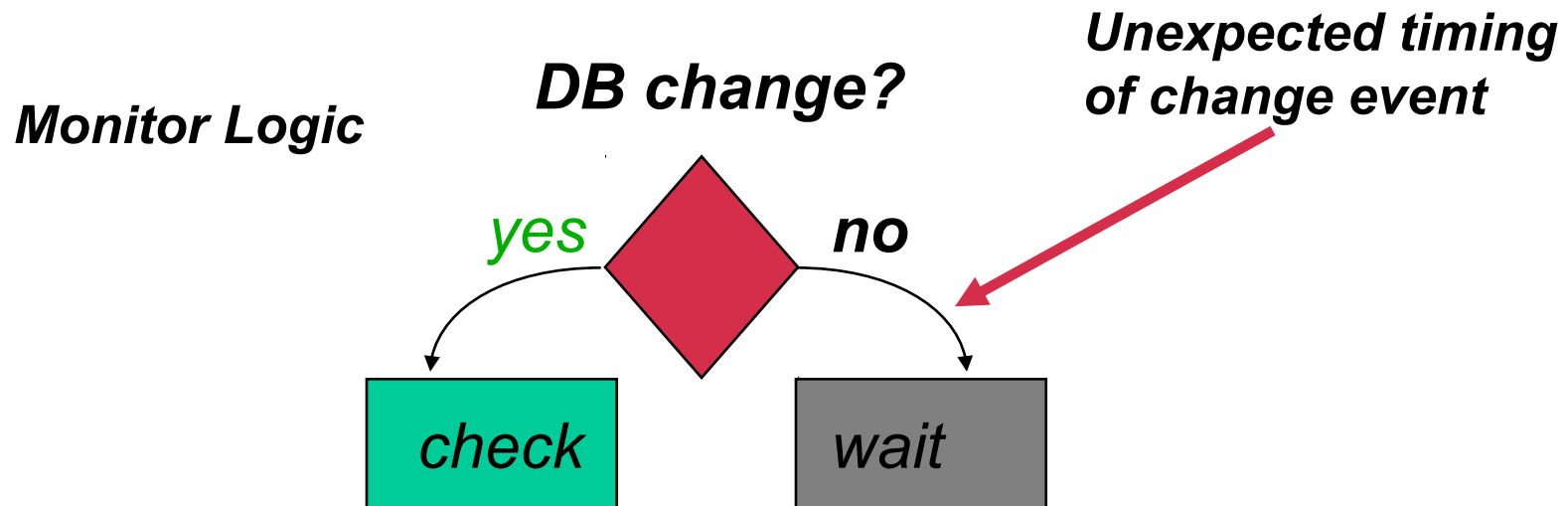
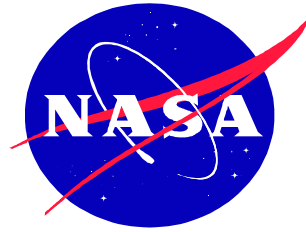


# Case Study: DS-1 Remote Agent



- Several person-months to create verification model.
- One person-week to run verification studies.

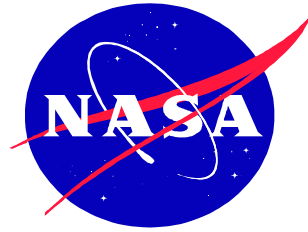
# Case Study: DS-1 Remote Agent



- Five difficult to find concurrency errors detected
- “[Model Checking] has had a substantial impact, helping the RA team improve the quality of the Executive well beyond what would otherwise have been produced.” - RA team
- During flight RA deadlocked (in code we didn’t analyze)
  - Found this deadlock with JPF



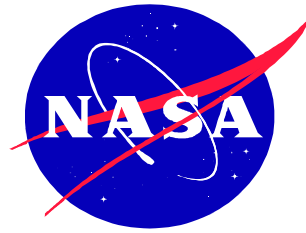
# DEOS Operating System



- Integrated Modular Avionics (IMA)
  - DEOS Guarantee Space and Time partitioning
- FAA Certification Process
  - Requires Structural Testing Coverage (MC/DC)
  - Inadequate for finding Time Partitioning Errors
    - Timing Error not found by Testing occurred
- Behavioral Analysis of Time Partitioning
  - NASA Ames and Honeywell HTC collaboration
  - Model Check slice of DEOS containing timing error



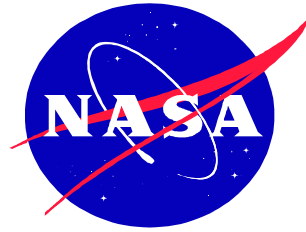
# DEOS Analysis



- Translated C++ 1-to-1 to PROMELA/SPIN (1500 lines of C++ code)
  - Found the time-partitioning error without any prior knowledge, what the error was, where it was or what made it show up.
  - Required very limited abstraction
- DEOS Team Reaction
  - Surprised that error was found by directly checking code
  - They expected NASA team to ask for smaller “slice”
  - They now have their own model checking group building on our work
- Then translated DEOS to Java and applied JPF
  - Backwards dependency analysis from the time partitioning assertion being checked revealed candidate variables to abstract
  - Applied “range” abstraction  $\{0,1,\text{many}\}$  to a specific integer variable
  - Too much of an over-approximation that led to many spurious errors
  - However with the choose-free heuristic *the* non-spurious error was found



# Analysis of the K9 Mars Rover



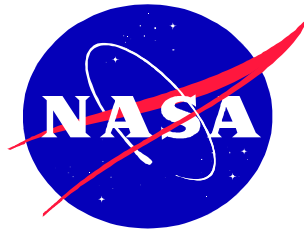
## *“The Experiment”*

- Rover is 8000 lines of code with 6 threads
  - heavy use of synchronization between the threads
  - Complex queue manipulation
- Purpose
  - Benchmark current state of the art in model checking, static analysis for runtime error detection and runtime analysis
  - Use traditional testing as baseline
  - Original code was in C++ that was translated to Java
    - About half the code was translated to C for the static analysis that used PolySpace
- Method
  - Controlled experiment: 4 groups of 2 people, each group uses one technology on the Mars rover code to find seeded bugs
  - 3 versions created and each group gets 2 days/version
  - Some bugs are removed/introduced between versions
  - Any new bugs discovered are not fixed, only known ones

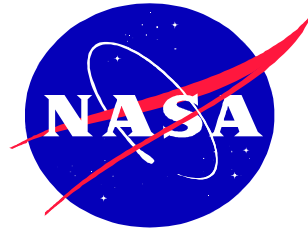


# Analysis of the K9 Mars Rover

## How did Model Checking do?



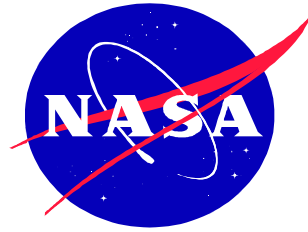
- Methodology for model checking
  - Asked never to “run” the code, only model check it
    - Keep the results clean from any testing influence
  - Code is heavily dependent on time
    - Given a gross over-approximation of time, where all time-related decisions became nondeterministic
- Found all, but one, of the known concurrency errors and some new ones
  - Better than any of the other teams
  - Only team that could always produce not just the error but how to get to it!
  - Also found all the non-concurrency errors
- Interesting observations
  - Abandoned the time abstraction within the first hour for one that is closer to real-time, but might miss errors
    - It was too hard for them to determine if errors were spurious not knowing the code well enough
  - Found a number of bugs in the first version, had a slow 2<sup>nd</sup> version, and then found all the remaining bugs in the 1<sup>st</sup> hour of the 3<sup>rd</sup> version
    - Took them some time to get their framework setup, but once done, they were flying



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# The Future of Software Model Checking



- Abstraction based approaches
  - Combine object abstractions (e.g. shape analysis) with predicate abstraction
  - Automation is crucial
- Symbolic Execution
  - Solving structural (object) and numerical constraints
  - Acceleration techniques (e.g. widening)
- Model checking as a companion to testing
  - Test-case generation by model checking
  - Runtime monitoring and model checking
- Modular model checking for software
  - Exploiting the interface between components
  - Interface automata (de Alfaro & Henzinger)
- Environment generation
  - How to derive a “test-harness” for a system to be model checked
- Result representation
  - Much overlooked, but without this we are nowhere!
  - “Analysis is necessary, but not sufficient” – Jon Pincus