

# 3. Formal Features of Petri Nets

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**Lecturer:**

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- 1) Reachability Graph
- 2) Boundedness
- 3) Liveness





# Content

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- ▶ Behavioral properties of petri nets
  - Reachability
  - Liveness
  - Boundedness
- ▶ Liveness checking

# Obligatory Readings

- ▶ T. Murata. **Petri Nets: properties, analysis, applications**. IEEE volume 77, No 4, 1989.
- ▶ Ghezzi Chapter 5
- ▶ J. B. Jörgensen. **Colored Petri Nets in UML-based Software Development – Designing Middleware for Pervasive Healthcare**. [www.pervasive.dk/publications/files/CPN02.pdf](http://www.pervasive.dk/publications/files/CPN02.pdf)

# Literature

- ▶ K. Jensen: **Colored Petri Nets**. Lecture Slides  
<http://www.daimi.aau.de/~kjensen> Many other links and informations, too
  - [www.daimi.aau.dk/CPnets](http://www.daimi.aau.dk/CPnets) the home page of CPN. Contains lots of example specifications. Very recommended
- ▶ W. Tichy. **Lectures on Software Engineering**. Karlsruhe University

# Literature

- ▶ K. Jensen, Colored Petri Nets. Vol. I-III. Springer, 1992-96. Landmark book series on CPN.
- ▶ W. Reisig. Elements of Distributed Algorithms – Modelling and Analysis with Petri Nets. Springer. 1998.
- ▶ W. Reisig, G. Rozenberg: Lectures on Petri Nets I+II, Lecture Notes in Computer Science, 1491+1492, Springer.
- ▶ J. Peterson. Petri Nets. ACM Computing Surveys, Vol 9, No 3, Sept 1977
- ▶ H. Balzert. Lehrbuch der Softwaretechnik. Verlag Spektrum der Wissenschaft. Heidelberg, Germany.

# Goals

- ▶ Understand the **isomorphism** between finite automata (statecharts) and bounded Petri nets
- ▶ Understand why Petri nets are useful



# 03b.1 Behavioral Properties of PN

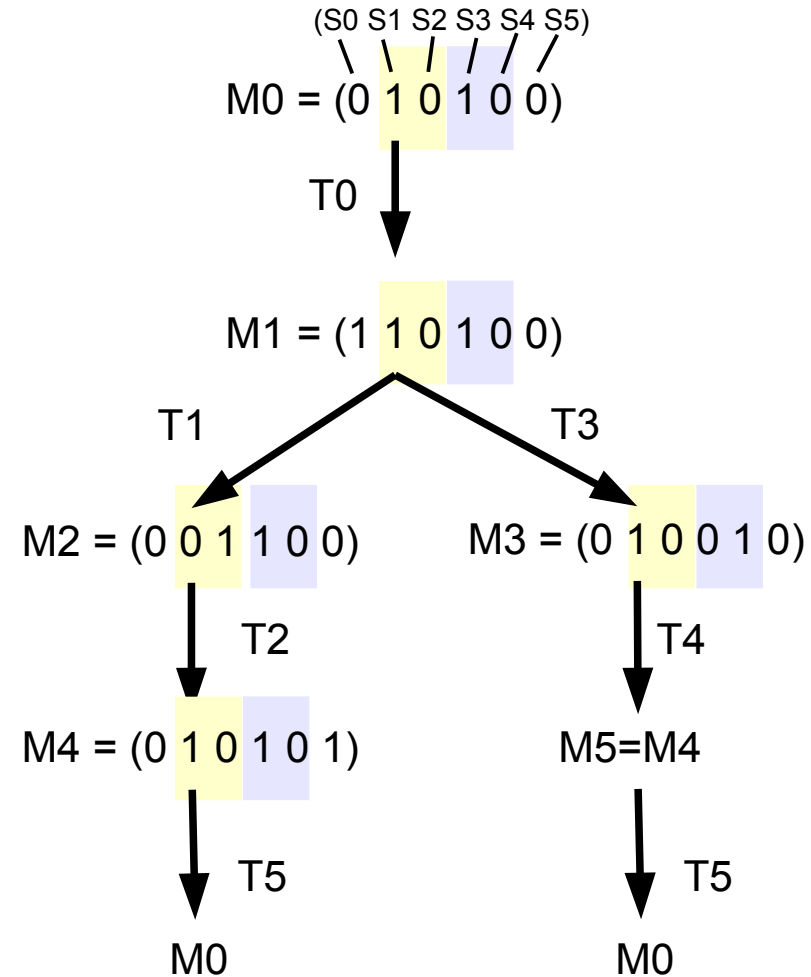
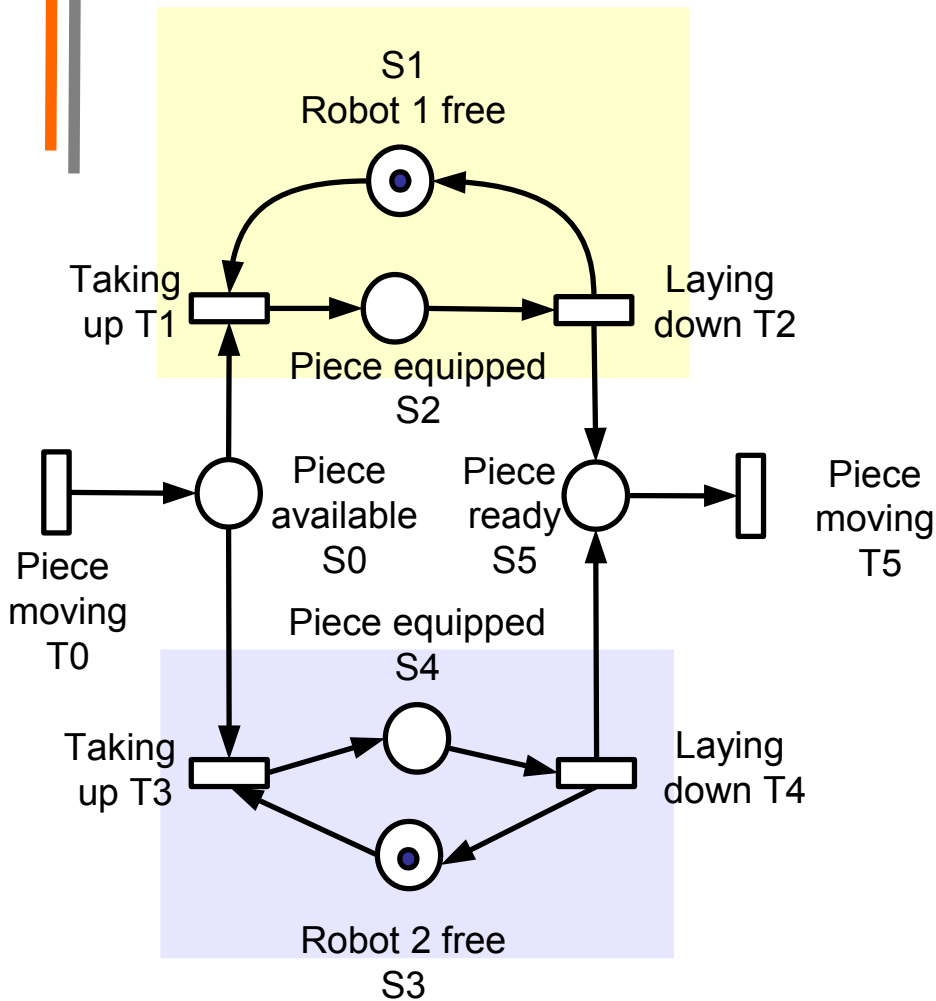


# Reachability of Markings

- ▶ If transaction  $t$  is *enabled* in the marking  $M$ , we write  $M[t)$
- ▶ A marking  $M_n$  is said to be *reachable* from a marking  $M_0$  if there exists a firing sequence  $s$  that transforms  $M_0$  to  $M_n$ .
  - We write this  $M_0[s) M_n$
- ▶ A *firing sequence* is denoted by a sequence of transitions  $s = M_0 [t_1) M_1 [t_2) M_2 \dots [t_n) M_n$  or simply  $s = t_1 t_2 t_3 \dots t_n$ .
- ▶ The set of all possible markings reachable from  $M_0$  is denoted  $R(M_0)$ .
  - $R(M_0)$  is spanning up a state automaton, the *state space*, **reachability graph**, or *occurrence graph*
    - Every marking of the PN is a state in the reachability graph
- ▶ The set of *all possible firing sequences* in a net  $(N, M_0)$  is denoted  $L(M_0)$ . This is the language of the automaton  $R(M_0)$ .



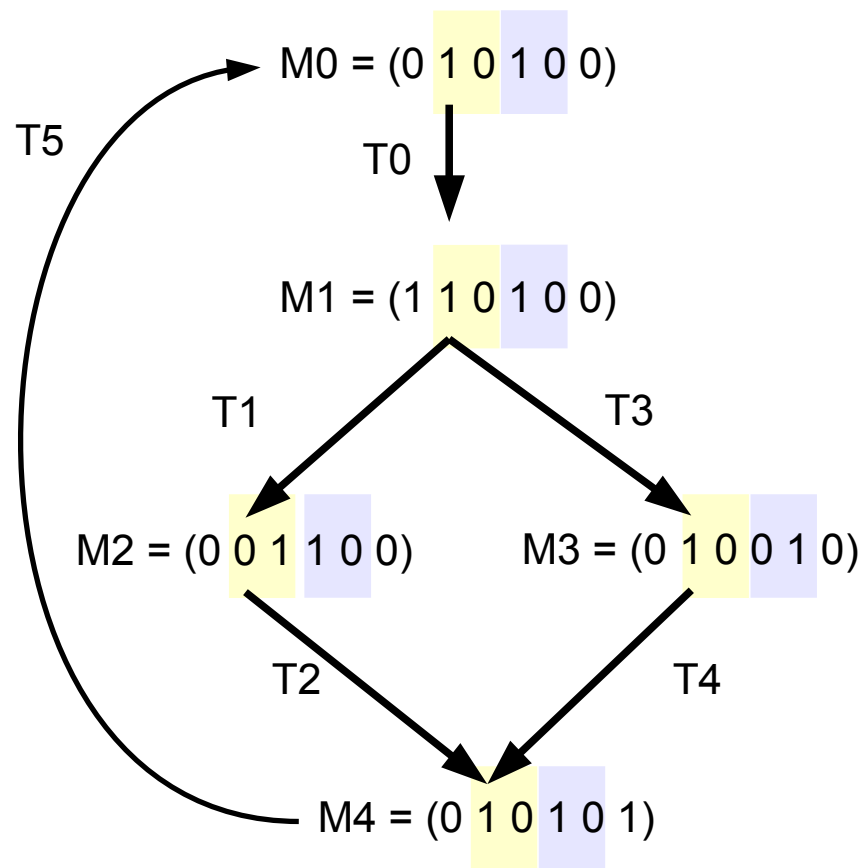
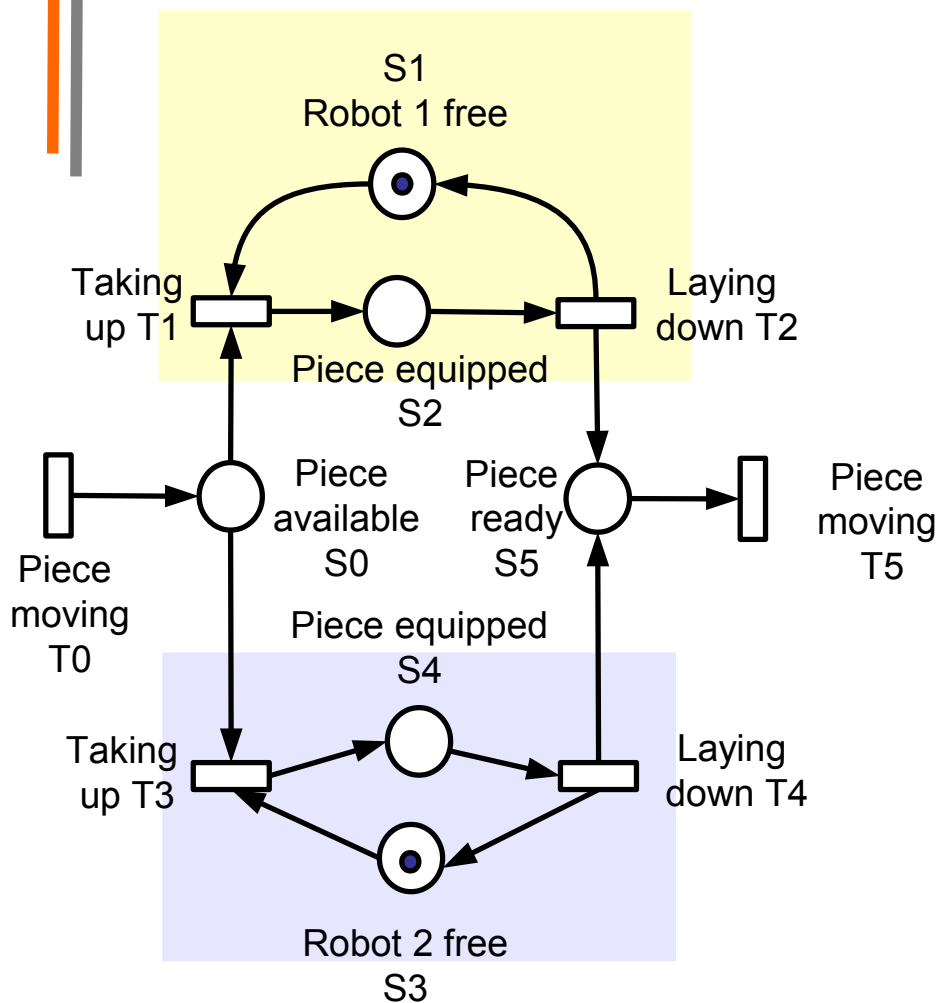
# Reachability Tree of the 2 Robots



Upper part of net (S1, S2)

Lower part of net (S3, S4)

# Folding the Tree to the Reachability Graph (Common Subtree Elimination)

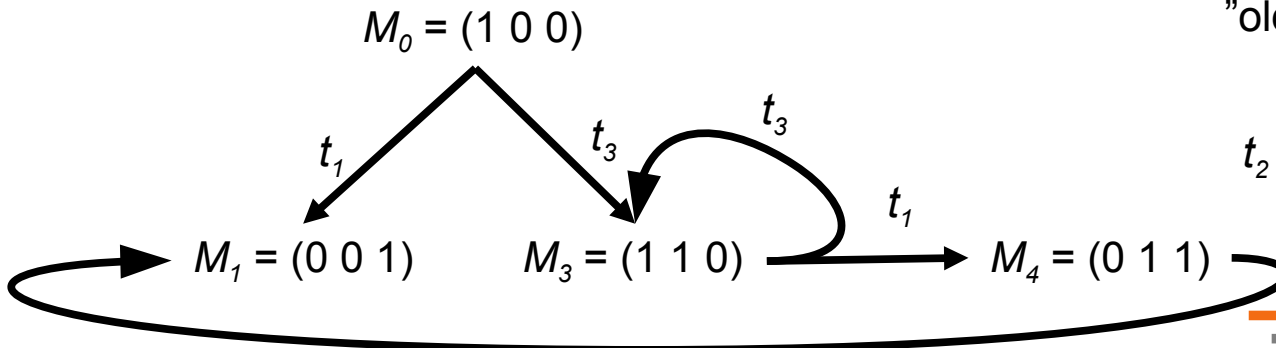
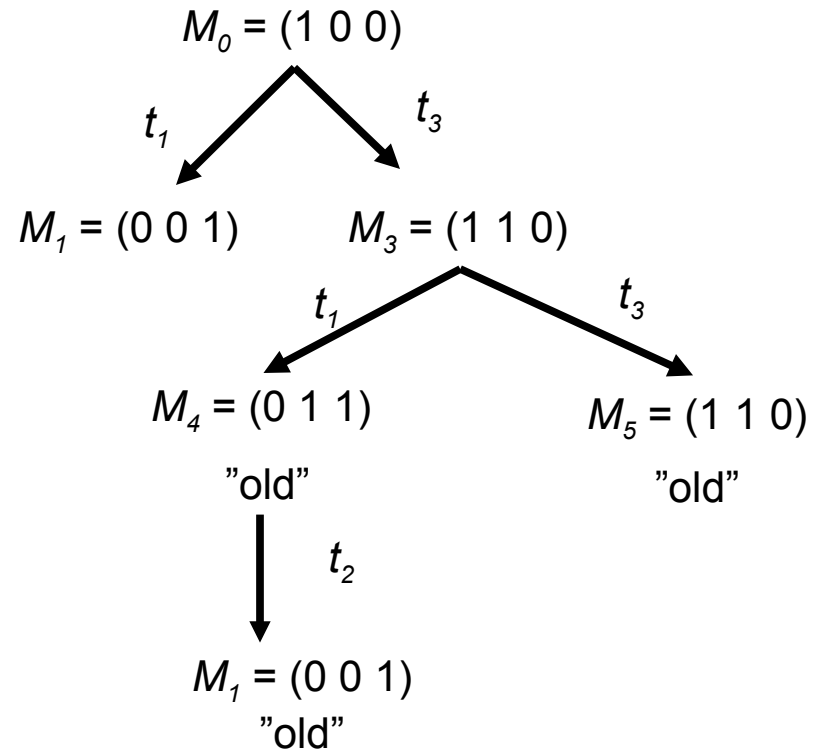
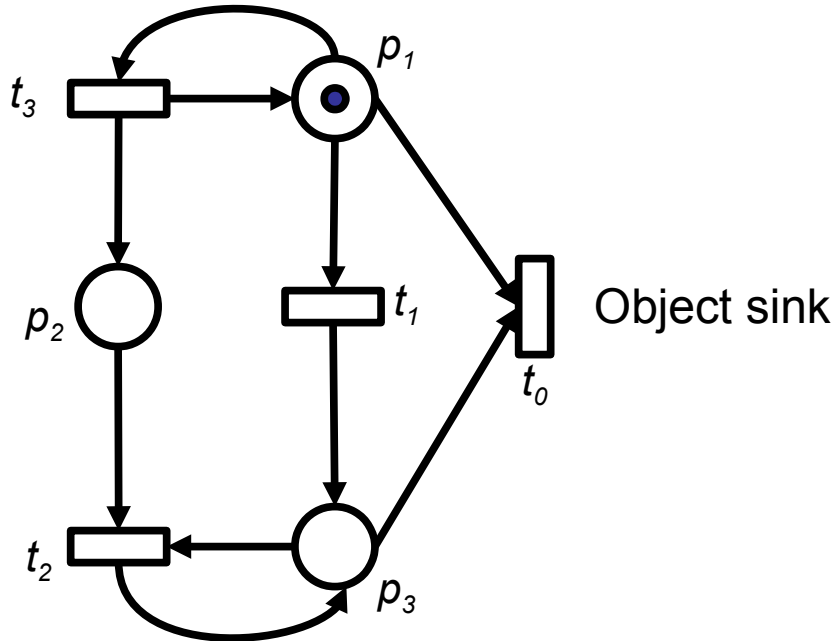


Upper part of net (S1, S2)

Lower part of net (S3, S4)

# Example: The Reachability Tree and Graph

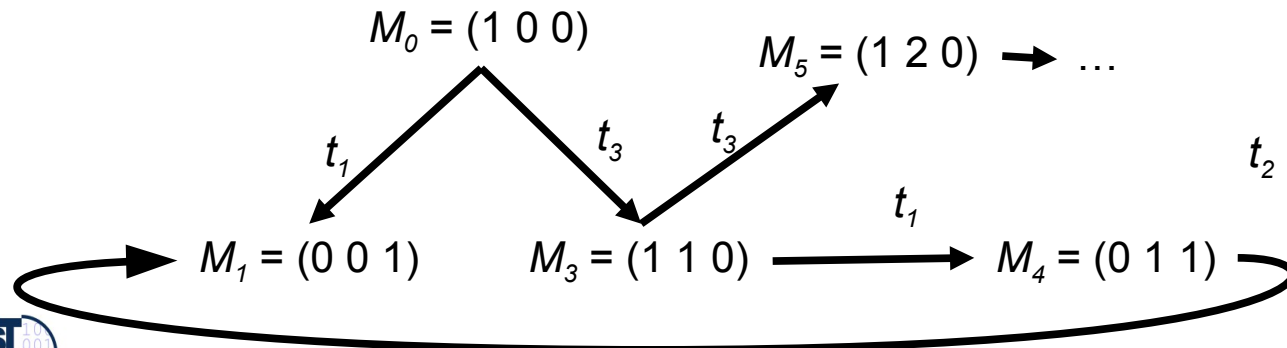
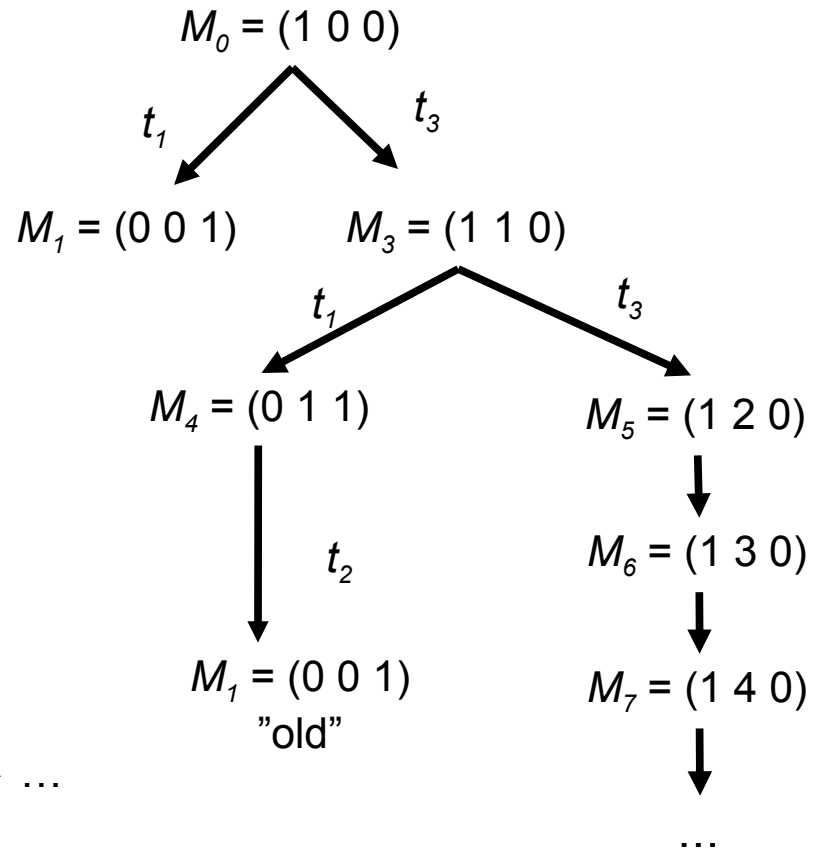
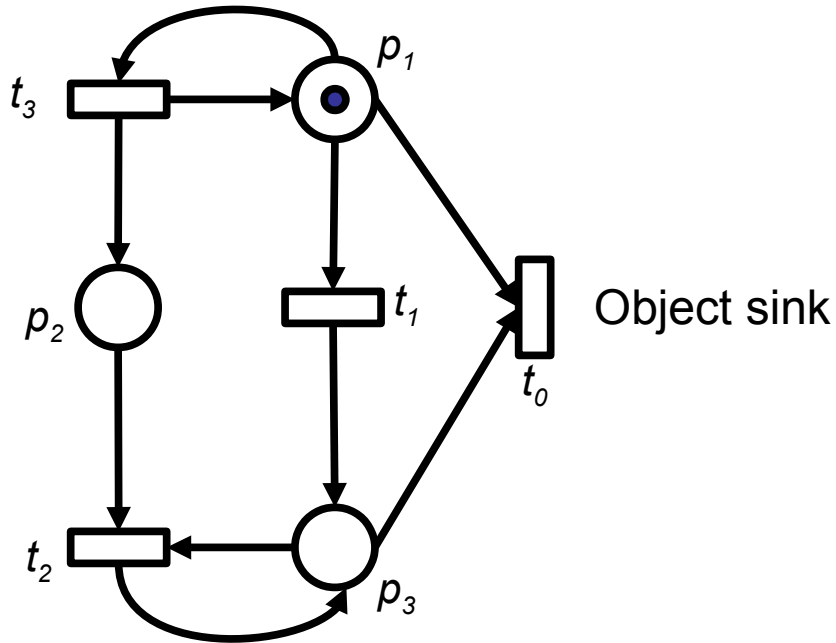
Only one token per place at a time.



# Boundedness and Safety

- ▶ A PN  $(N, M_0)$  is *k-bounded* or simply *bounded* if every place is size-restricted by  $k$ 
  - $M(p) \leq k$  for every place  $p$  and every marking  $M$  in  $R(M_0)$ .
- ▶ A PN is *safe* if it is 1-bounded.
- ▶ Bounded nets can have only finitely many states, since the number of tokens and token combinations is limited
  - The reachability graph of bounded nets is finite, it corresponds to a finite automaton (which is much larger)
  - The PN is much more compact, it *abbreviates* the automaton

# Example: Unbounded net



# Applications of Boundedness

- ▶ The markings of a state can express the number of available resources
  - Operating Systems: number of memory blocks, number of open devices, number of open files, number of processes
  - Workflows: number of actors, number of workpieces that flow
- ▶ Boundedness can be used to prove that a system consumes  $k$  resources at most
  - Important for systems with resource constraints

# Liveness of Nets

- ▶ Liveness is closely related to the complete absence of deadlocks in operating systems.
- ▶ A PN  $(N, M_0)$  is **live** if, no matter what marking has been reached from  $M_0$ ,
  - all transitions are live
  - i.e., it is possible to fire any transition of the net by progressing through some further firing sequence.

# Liveness of Transitions

- ▶ Liveness expresses whether a transition stays active or not

A transition  $t$  is called:

- ▶ *Dead (L0-live)* if  $t$  can never be fired in any firing sequence in  $R(M_0)$ . (not fireable)
- ▶ *L1-live (potentially fireable)* if  $t$  can be at least fired once in some firing sequence in  $R(M_0)$ . (firing at least once from the start configuration)
- ▶ *L2-live ( $k$ -fireable)* if  $t$  can be fired at least  $k$  times in some firing sequence in  $R(M_0)$ , given a positive integer  $k$ . (firing  $k$  times from the start configuration)
- ▶ *L3-live (inf-fireable)* if  $t$  appears infinitely often in *some* firing sequence in  $R(M_0)$ . (firing infinitely often from the start configuration)
- ▶ *live (L4-live)* if  $t$  is L1-live for every marking  $M$  in  $R(M_0)$ . (This is more:  $t$  is always fireable again in a reachable marking)

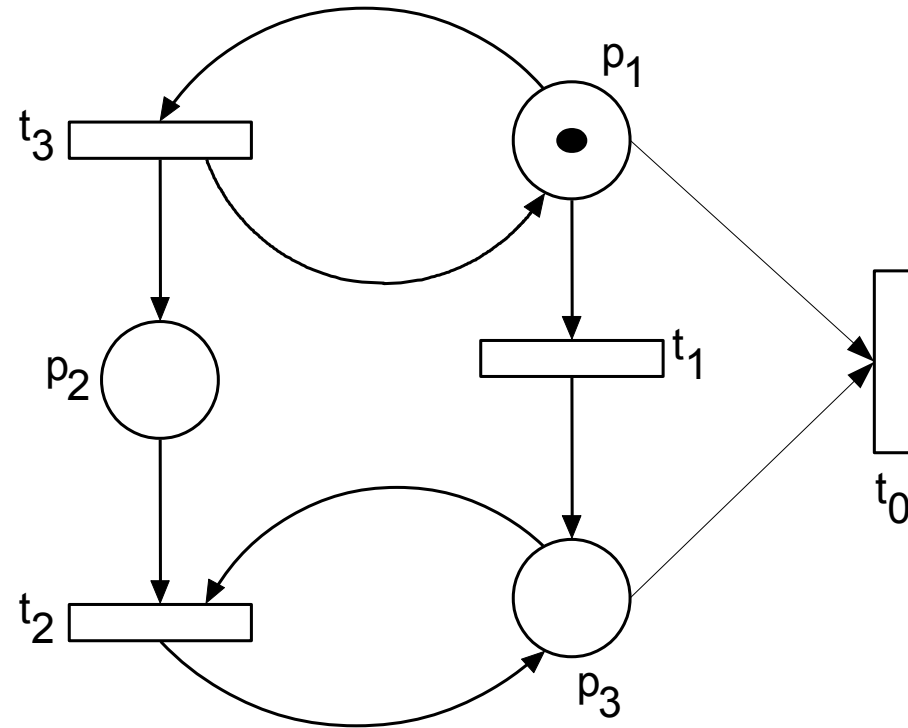


# Liveness of Markings and Nets

- ▶ A marking is *dead* if no transition is enabled.
- ▶ A marking is *live* if no reachable marking is dead (equivalent: all transitions are live)
- ▶ A net is *live* if  $M_0$  is live (every  $t$  is always fire-able again from every reachable marking of  $M_0$  )

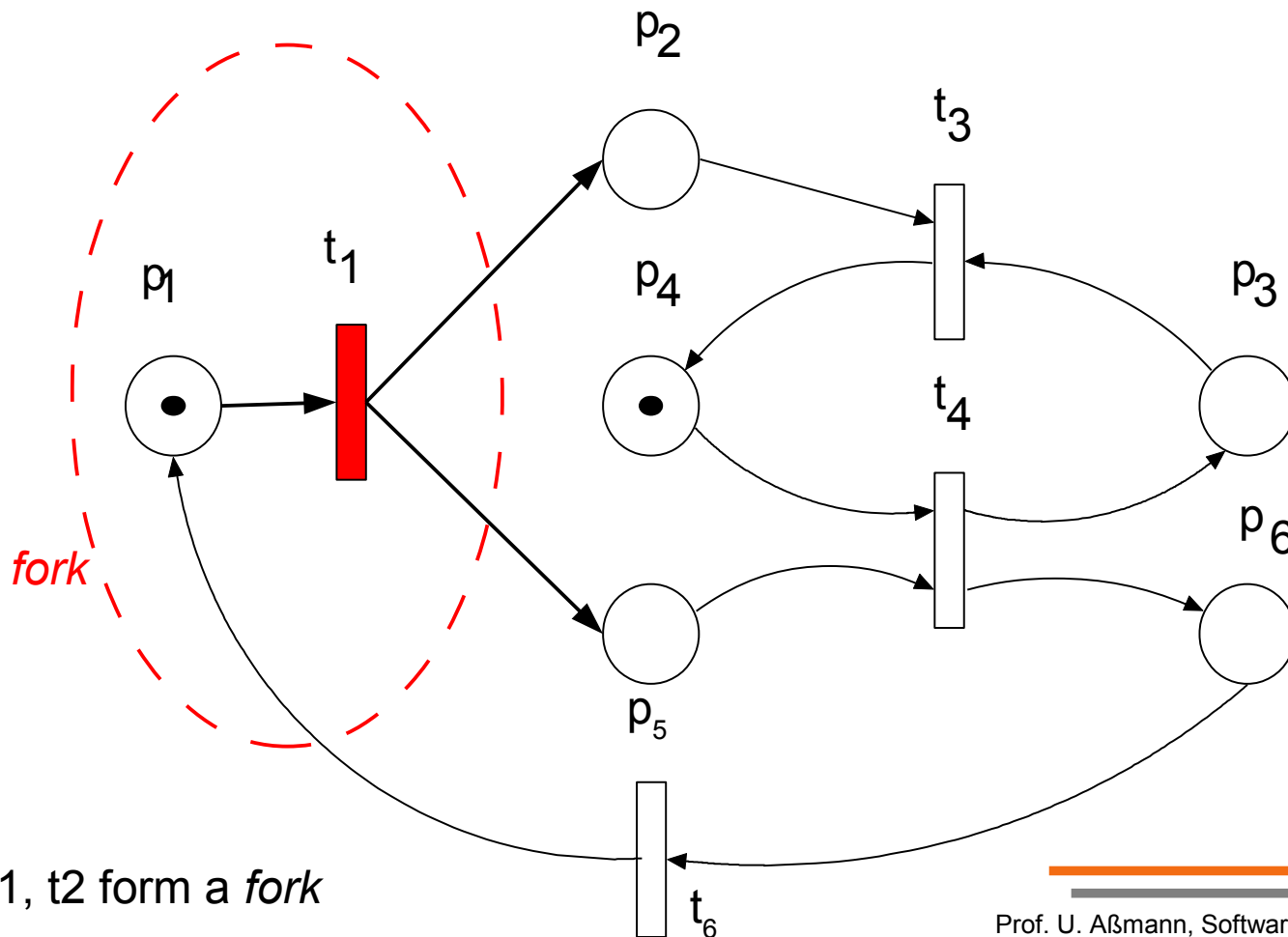
# Example: Liveness

- ▶ Assumption: net is boolean
- ▶  $t_1$  L1-live (fireable only once, bridge)
- ▶ Hence,  $t_3$  is L3-live (on a cycle), but not L4-live, since it cannot be activated anymore once  $t_1$  is crossed
- ▶  $t_0$  is L0-live (dead, since  $t_1$  is bridge and either  $p_1$  or  $p_3$  is filled)
- ▶  $t_2$  L2-live (fireable when  $t_1$  is crossed)



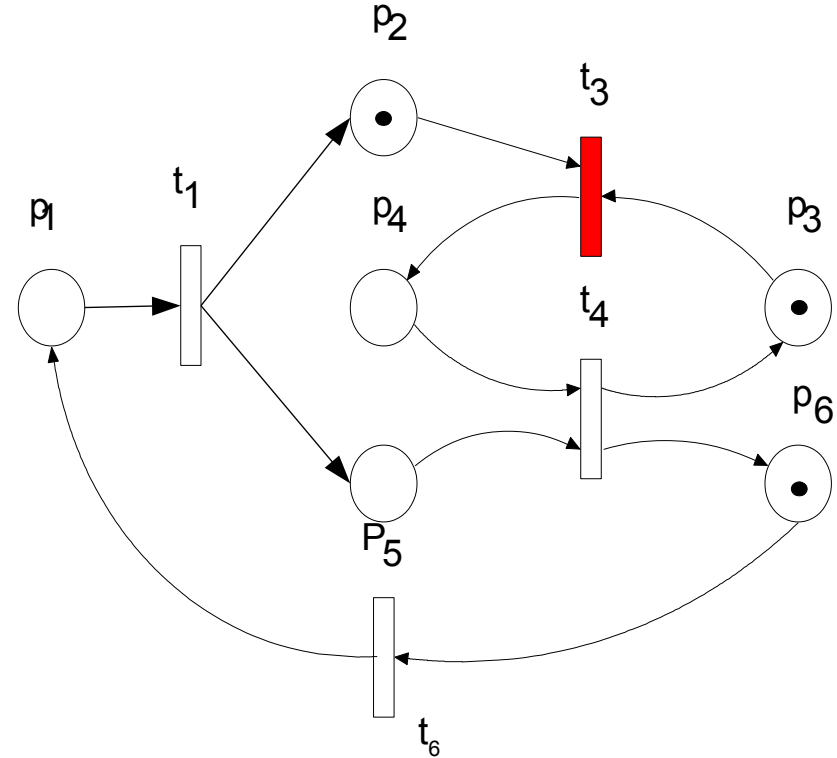
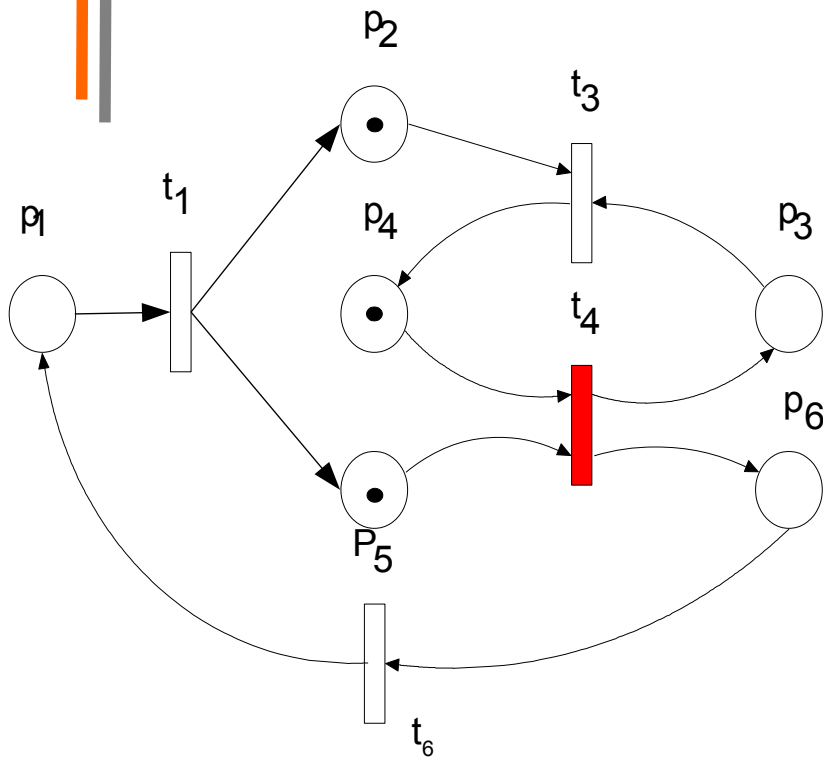
# Example: Liveness

- ▶ A safe, live PN. M0 can be reproduced again, e.g., with t1 t2 t4 t3 t6 reproduces a filled p1 and p2



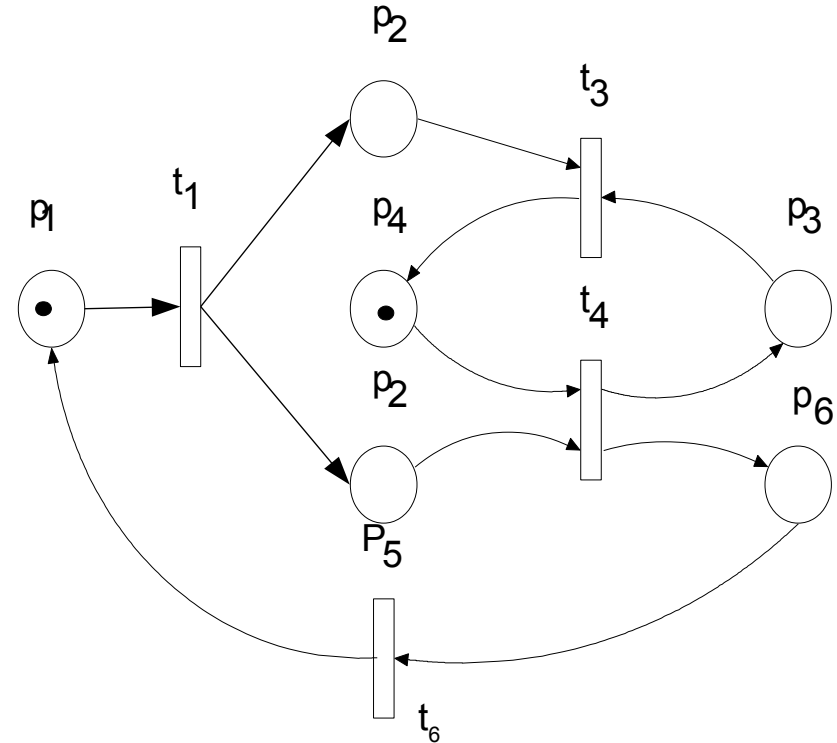
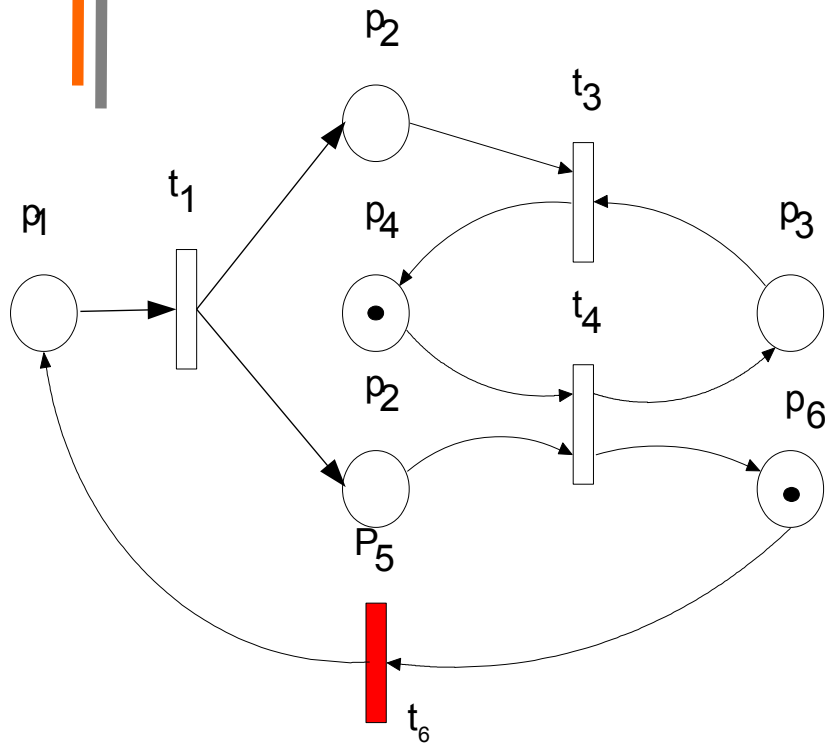
p1, t1, t2 form a *fork*

# Example: Liveness



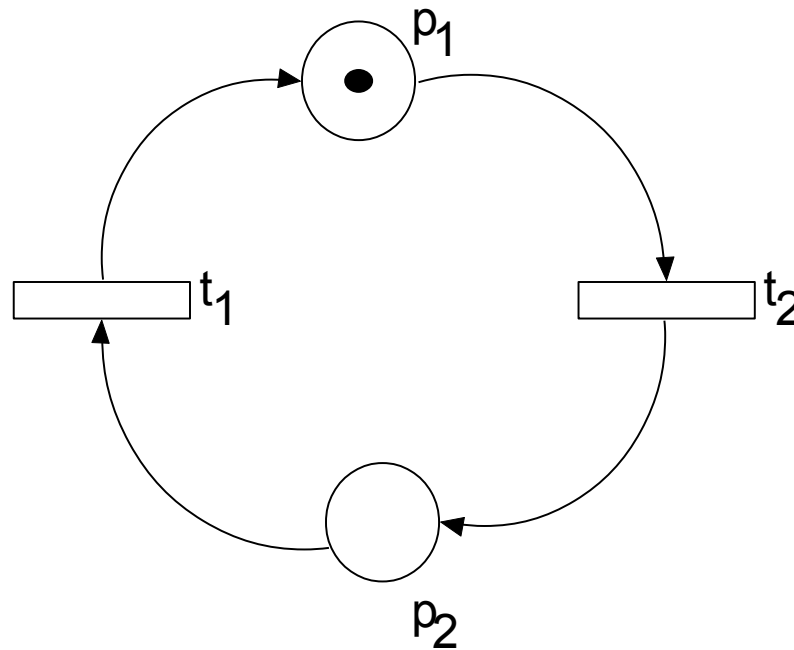
p2 is a synchronization dependency; process p5 can run earlier, p2 has to wait.  
 Note: the content of p2 must be reproduced again

# Example: Liveness



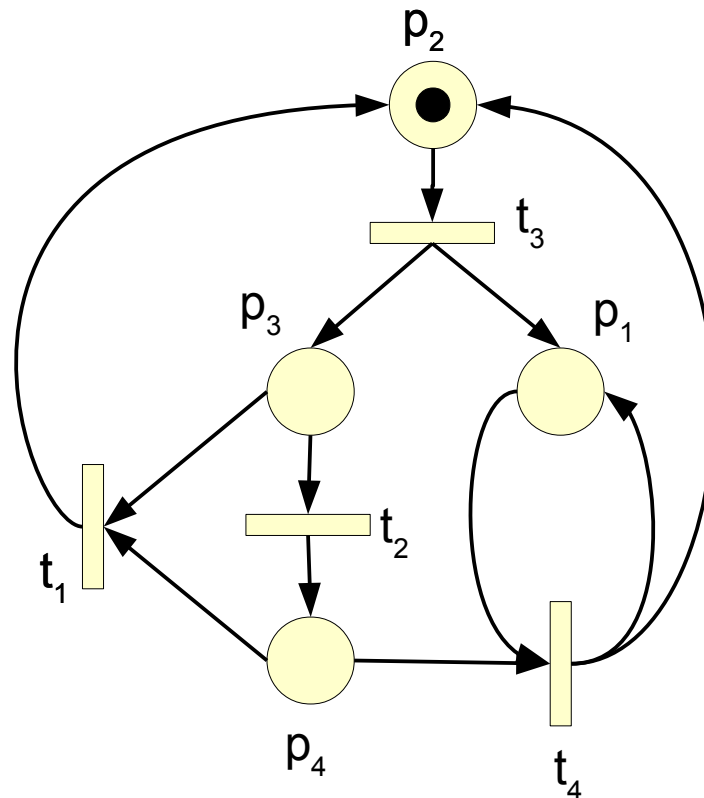
Net is unbounded, due to the reproduction facilities of  $t_6$ ,  
 i.e., running  $t_6$  before  $t_3$ :  
 $t_1 \ t_2 \ t_4 \ t_6 \ t_1 \ t_2 \ t_4 \ t_6 \ \dots$

# Well, everything: Safe, Live



# Not Bounded, Not Live

- ▶ Not live, because  $t_1$  is never enabled
- ▶ Unbounded:  
(0100)  $t_3$  (1010)  $t_2$  (1001)  $t_4$   
(2100)  $t_3$  (2010)  $t_2$  (2001)  $t_4$   
(3100) ...



# What have we learned?

- ▶ Behavioral properties of petri nets
  - Reachability
  - Liveness
  - Boundedness
- ▶ Formal approaches (matrix algebra) out of this lectures scope



# The End