

14. Layers of M2 in a Technical Space (Language Families and Composition of Tools)

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- 1) Problem of Tool Composition
- 2) Data definition languages
- 3) Query languages
- 4) Constraint languages
- 5) Reuse languages
- 6) Transformation and Restructuring languages
- 7) Behavior specification languages
- 8) Language families in several technical spaces
- 9) .. and all together now...



Die Metasprachen bzw DDL müssen auseinander aufgebaut werden.

Obligatory Literature

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Other Literature

4 Model-Driven Software Development in Technical Spaces (MOST)

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 - McMenamin, S., Palmer, J.: Strukturierte Systemanalyse; Hanser Verlag 1988
- Workflow languages:
 - ARIS tool (IDS Scheer, now Software AG)
 - http://en.wikipedia.org/wiki/
 Architecture_of_Integrated_Information_Systems
- ▶ Big CASE IDE
 - MID Innovator (insbesondere f
 ür Informationssysteme)
 - http://www.modellerfolg.de/
 - MagicDraw http://www.nomagic.com/

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14.1 Basic Techniques of Software Engineering, Language Families, and Tool Composition

Technical Space Tracing, Regeneration, Synchronization Model Management Composition, Mapping, Transformation Model Analysis Querying, Attribution, Analysis, Interpretation Metapyramid (Metahierarchy)

Metamodel Layering for Language Families

8 Model-Driven Software Development in Technical Spaces (MOST)

- M2 can systematically be divided into M2 layers (metamodel layer cake)
 - with metamodel packages in language families for:
 - Language engineering by composition
 - Tool construction by composition
 - Method and process engineering by composition of basic techniques
- ► Improves Tool engineering, Productivity of Process (Process Engineering), Test engineering, Simulation engineering
- Indirectly: Reliability of Software, Evolvability
- Different forms of Systems need different M2 layers:

Cyber-Physical Systems

Software Systems

Information Systems

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Basic Language Families (Layer Structure of M2, Metamodel Layer Cake) Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) Information Systems DCL CCL DRL CRL DQL CQL DDL CDL Data and code Data and code Data definition Data and code constraint reuse languages query languages languages languages Pattern languages **M2** S-languages (Synthesis) Software Systems DTL CTL DRL CRL Data and code restructuring transformation languages languages M-languages (Modifying) Cyber-Physical Systems BSL DML CML SIL Behavior Data manipulation Simulation specification languages languages languages ST)

Basic Language Families (Structure of M2)

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- Data and code modeling with definition languages (DDL, CDL)
 - DDL form the basic packages of M2 to be imported by all other packages
 - Ex: lifted metamodels, such as EBNF-Grammars, Relational Schema (RS), Entity-Relationship-Diagrams (ERD), UML-CD, SysML-Component diagrams
 - In the metahierarchy, code covers M3-M0, because M0 is populated by objects of the dynamic semantics
 - Data does not have dynamic semantics, so it only covers M3-M1 (or M2-M0); however, when data is loaded as code, it changes its nature.
- Analysis languages (A-languages):

Information Systems

- Queries with query languages (DQL, CQL)
- Consistency checking with data and code constraint languages (DCL, CCL) on wellformedness of data and code
- Reuse languages: Contract languages and composition languages
 - · Architectural description languages (ADL)
 - Template-Sprachen (template languages, TL) → course CBSE

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Basic Language Families (Structure of M2) (ctd.)

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Synthesis languages (S-languages)

Software Systems

- Declarative Transformation Languages (DTL, CTL)
 - · Data flow diagrams (DFD)
 - · Term- und graph rewrite systems
 - XML transformation languages
- Restructuring Languages (transformation languages retaining semantics, DRL, CRL)
 - Wide Spectrum Languages for refinement (broadband languages, Breitbandsprachen)
 - Data exchange languages (data exchange languages

Cyber-Physical Systems

- Data and State Manipulation Languages (M-languages)
 - (non-declarative) Data manipulation languages (DML)
 - · Workflow Languages, Petri Nets, Imperative languages
- Languages for behavior specification language (BSL)
 - Action-based state transition systems (finite automata and transducers)
 - Condition-Action-languages, Event-Condition-Action-languages (ECA)
- ► **Simulation languages** (Modelica, Simulink, OpenFoam) for discrete, continuous, and hybrd systems

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CPS and **Simulation**

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Software Engineering of Heterogeneous Systems

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- A software factory uses many base techniques and languages
- There is no homogeneous software construction
- Example: New electric car platform of VW and its design tool

A **software factory** is an environment to produce software and CPS product lines

- based on metamodeling, macromodels and pattern languages
- in one technical space or bridging several technical spaces

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How to compose *languages* for a heterogeneous software factory?



14.2 Data Definition Languages (DDL) and Code Definition Languages (CDL)

The basic layer of M2 Usually lifted to M3 (i.e., self-descriptive)

All materials are shaped by a DDL or CDL



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Data Dictionaries (Data Catalogues) as Basis for all Tools and IDE

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- A data dictionary (data schema) contains all types of data flowing through a system, including those stored in a repository (on M1)
 - Scope: local for an application, for several applications, for an entire company or even for a supply chain
 - A data dictionary is a special kind of model repository
 - If the data are models, it is called **metamodel repository**
- A homogeneous data dictionary is specified in a DDL
 - EBNF defines text languages (sets of text types)
 - Relational Schema (RS) defines relations and tabels
 - XML Schema (XSD) defines tree languages
 - ERD or UML-CD define graph languages
- A heterogeneous data dictionary is specified in several DDL
 - Usually, software factories maintain heterogeneous metamodel repositories

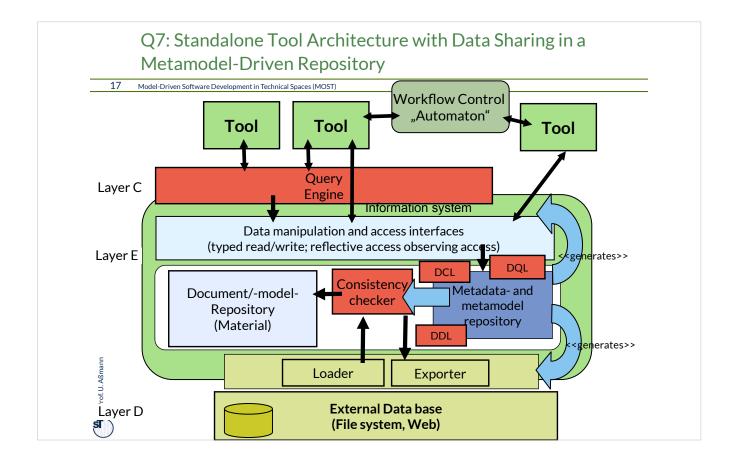
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Information Systems are based on DDL

Model-Driven Software Development in Technical Spaces (MOST)

- An **information system** is a software system conducting data analysis about a repository
 - Data warehouses, business intelligence, data analytics
- A **stream-based information system** is a software system conducting data analysis on a set of data streams
- Every software tool, every IDE, every software factory relies on an information system
 - maintaining artefacts (data, programs, models, documents)
 - giving information about them
 - typed by the types in a data dictionary
- The data dictionary is described in a data definition language (DDL) or code definition language (CDL)
- ▶ The repository and the data streams are queried and analyzed by A-languages

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A microtool is a function in a tool usually implemented as a Command Object.



14.3 Query Languages (QL)

DQL - Data Query Languages CQL - Code Query Languages

All materials are queried by technical tools shaped by a DQL or CQL.



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DQL and CQL

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- Querying a tool's internal repository
 - Pattern matching of structural patterns
 - Joining information
 - Reachability queries
- Metrics : counting of patterns
- Analysis: Deeper knowledge (implicit knowledge)
 - Program and model analyses on value and type flow

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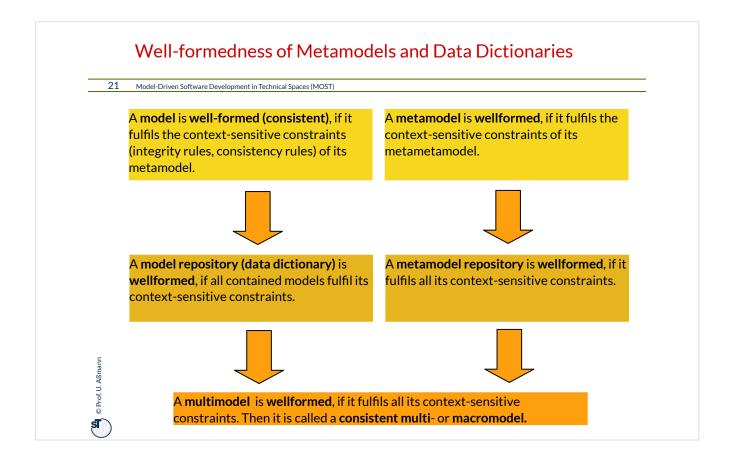


14.4 Constraint Languages (DCL,CCL) for Consistency Checking

All materials are constraint-checked by technical tools shaped by a DCL or CCL.



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Das hier muss eigentlich nach der DCL gelehrt werden

A **reuse language** is a (sub-)language) controlling the reuse of program or model elements (modularity).

Examples:

- Visibility languages define constructs for the visibility and reuse of model elements
- Contract languages check whether components, modules, classes, procedures and methods are applied correctly
- Interface definition languages describe types for interfaces in different languages, for heterogeneous software
 - see course CBSE
- Component model definition languages define reuse languages and contract languages [Johannes-PhD]



Das hier muss eigentlich nach der DCL gelehrt werden



14.5 Data Transformation Languages (DTL)

Text, XML, Term, and Graph Rewriting see separate Chapter



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DTL and **DML**

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- A DML (data manipulation language, Datenmanipulationssprachen) is used to transform data
- ▶ **Declarative DTL (Datentransformationssprachen, DTL)** consist of declarative rule systems transforming a repository
 - Term rewriting for trees, terms, link trees, and XML trees
 - Graph rewriting for graphs
- ▶ Imperative DML (general DML) know states and side effects.

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Restructuring Languages (DRL)

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- Restructuring means to transform while to retain invariants.
- A **restructuring language** is a DTL giving guarantees about the transformed materials.
- A refactoring language restructures code and retains some of its invariants
- Languages for **Refinement**:
 - Refinement means that a transformed program implies the semantics of the original
 - A wide spectrum language transforms programs by refinement, generating more and more versions *implying* the requirements specification (the original)

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14.6. Behavior Specification Languages (BSL)

All automata (workflow engines) in a TS execute workflows written in a BSL.

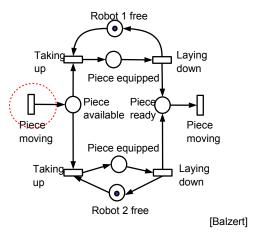


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Automaten, Petri-Nets, DFD and Workflow Languages

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- State-oriented Behavior specification languages enable the specification of interpreters (operational dynamic semantics) and simulators (interpreters with a specific platform)
- ► Automata, Transducers, Statecharts → course Softwaretechnologie-I
- ► DFD, Petri-Nets and Workflow languages → course Softwaretechnologie-II
- ► Event-condition-action languages (ECA languages) → course Softwaretechnologie-II



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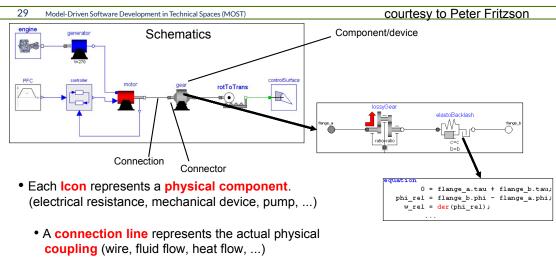


14.6.1. Simulation Languages (SL)



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Modelica Users View



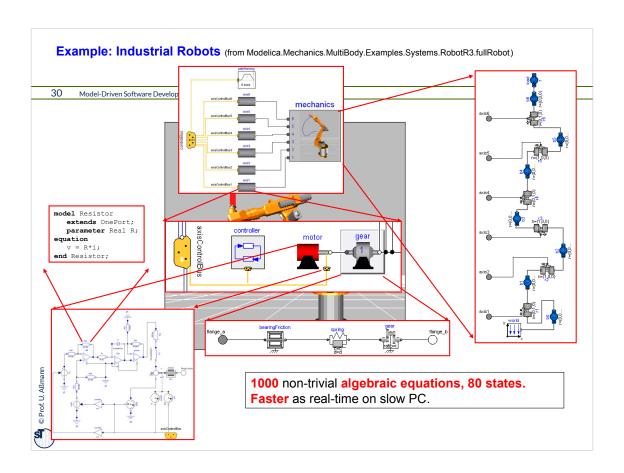
• A component consists of **connected** sub-components (= hierarchical structure) and/or is described by equations.

$$0 = \mathbf{f}(\dot{\mathbf{x}}(t), \mathbf{x}(t), \mathbf{y}(t), t)$$

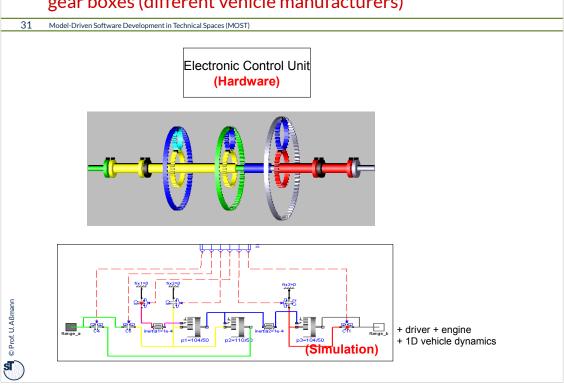
• By **symbolic** algorithms, the high level Modelica description is transformed into a set of explicit differential equations:

$$\dot{\mathbf{x}}(t) = \mathbf{f}(\mathbf{x}(t), t)$$

$$\mathbf{y}(t) = \mathbf{f}(\mathbf{x}(t), t)$$



Example: Hardware-in-the-Loop Simulation of automatic gear boxes (different vehicle manufacturers)





14.7 Examples of Language Families on the M2 Layers

Every technical space has a language hierarchy on M2 with a similar, layered structure.

All tools have an underlying language family.

Every IDE has an underlying language family.



Every software factory has several underlying language family.

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Basic Language Families (Layer Structure of M2) 33 Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) Materials DCL CCL DRL CRL DDL CDL DQL CQL Data and code Data and code Data definition Data and code constraint reuse query languages languages languages languages S-languages (Synthesis) Tools DTL CTL **DRSL CRSL** Data and code restructuring transformationlanguages languages M-languages (Modifying) Automata BSL **DML CML** SIL Behavior Data manipulation Simulation specification languages languages languages

UML Language Family in the ModelWare TS 34 Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DCL CCL DDL CDL UML-CD DRL CRL DQL CQL OCL OCL pre- and Sequence D. OCL UML-OD postconditions UML Comp.D. Commun.D. S-languages (Synthesis) **DRSL CRSL** DTL CTL Activity diagrams Packages, merge operator M-languages (Modifying) SIL DML CML **BSL** Simulink/ Statecharts SysML Blocks

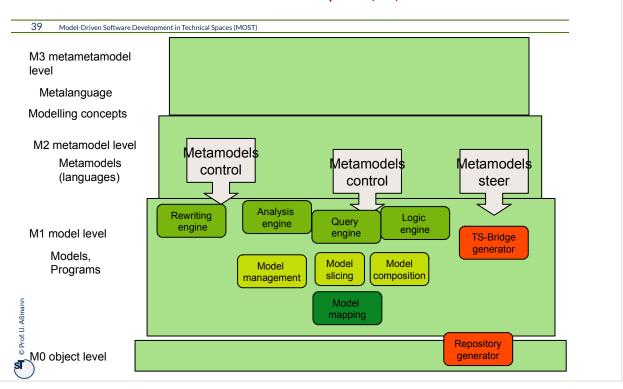
ERD/RS Language Family in the Relational TS 35 Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DCL CCL **DRL CRL** DDL CDL RS, ERD DQL CQL Integrity constraints SQL built into SQL S-languages (Synthesis) DTL CTL **DRSL CRSL Event-Trigger** Packagesr languages M-languages (Modifying) © Prof. U. Aßmann DML CML Update BSL SIL languages

XML Language Family in the Link Tree TS 36 Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DCL CCL DRL CRL DDL CDL DQL CQL Integrity constraints XML DTD, XSD, RelaxNG namespaces, WSDL Xquery, Xcerpt built into SQL S-languages (Synthesis) DTL CTL **DRSL CRSL** Xcerpt, XSLT, XChange M-languages (Modifying) DML CML BSL SIL

GrUML Language Family [Ebert, U Koblenz] 37 Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DDL CDL GREQL DQL CQL GREQL DRL CRL S-languages (Synthesis) DTL CTL GRETL M-languages (Modifying) DML CML BSL SIL

.QL Language Family [Semmle, github] 38 Model Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DDL CDL Java DQL CQL QL DRL CRL S-languages (Synthesis) DTL CTL DRSL CRSL M-languages (Modifying) DML CML BSL SIL

The Generic Tools of a Technical Space (TS)



The Generic Tools of a Technical Space (2) 40 Model-Driven Software Develop M3 metametamodel Metalanguage Metalanguage level controls steers Metalanguage Modelling concepts Rewriting engine Metamodel Metamodel Metamodel management M2 metamodel level exchange mapping Metamodels Analysis engine Metamodel Metamodel (languages) composition Metamodel Logic engine Repository generator

M1 model level

Models,

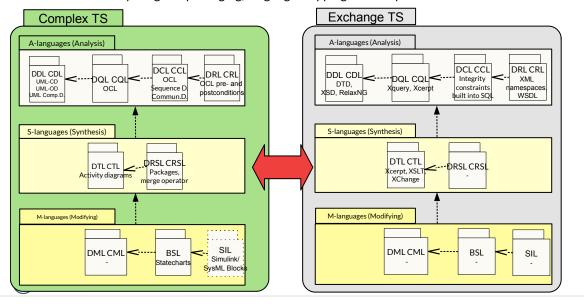
Programs

M0 object level

Technical Space Bridges with Exchange TS

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- Complex technical spaces must be flattened to a textual exchange TS (here XML)
- Due to layering and packaging, language mappings are simpler





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14.8. ... and all together now...



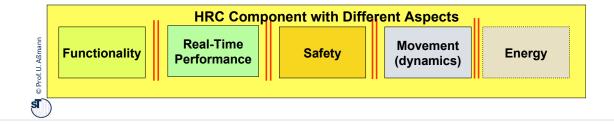
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Example Megamodel: Composition of Contracts in the HRC (Heterogeneous Rich Components) MDSD Tool Chain for Complex Embedded Systems

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[courtesy to Vered Gafni]

- Within a HRC component, contracts in different views can be synchronized (synchronized token-based modeling) [Damm]
 - The real-time assertions can be coupled with functional, real-time, safety, physical movement (dynamics), and energy view
 - Every contract has a different contract language
- Between different components, the contracts of a certain viewpoint can be composed and checked (viewpoint-specific modeling)



Example Megamodel: HRC Language Family for Safety-Critical Embedded Software Model-Driven Software Development in Technical Spaces (MOST) A-languages (Analysis) DRL CRL DCL CCL HRC components HRC contract language DQL CQL DDL CDL OCL MOF Safety specifications S-languages (Synthesis) DTL CTL **DRSL CRSL** M-languages (Modifying) BSL SIL DML CML Real-time automata Simulation Hybrid automata languages

Energy automata



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14.8.1. Technical Space Bridges and the Metamodel Layer Cake



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Why is it Important to Know about the M2-Layers?

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The multimodels managed by software factories combine different languages from several layers of M2 (**M2-Mix**)

- ▶ ERD MOF XSD UML-CD
- Xquery XSLT SQL SPARQL
- OCL SpiderDiagrams OntologyLanguages
- ▶ Java C++ C#
- Petrinets DFD WorkflowNets BPMN

Domain-specific languages always consist of an M2-Mix

Methods also



Why is it Important to Know about the M2-Structure?

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How can we compose metamodels for tool composition?

- Language families can be arranged in M2 layers
 - Many languages on upper layers can be composed with languages on lower layers
- If everything is in one Technical Space, composition of tools relies on the composition of languages
 - For that we need Model Composition Systems (forthcoming, → course CBSE)
 - · Example: UML-Package Merge-Operator

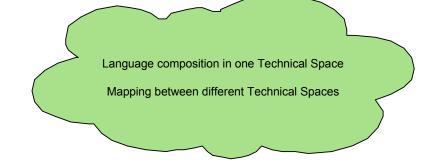
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Language composition: Compose new language constructs from layers further down



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If we have to treat several Technical Spaces, Bridges between TS have to be built



The End - Exam Questions

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- ▶ Where would you position a query tool on M1 in the tools layer or in the materials layer? Does the tool's metamodel in its query language belong then to the tools metamodel layer of M2 or to the materials metamodel layer?
- Why can we compose different DQL with a given DDL?
- ▶ How is it possible to apply a graph query language on XML trees?
- Why is UML such a complex language?
- A MDSD tool chain such as the HRC IDE for embedded systems works with many languages in different technical spaces. Explain some ingredients of such a complex IDE.

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