

## 14. Layers of M2 in a Technical Space (Language Families and Composition of Tools)

Prof. Dr. U. Aßmann

Technische Universität Dresden

Institut für Software- und

Multimediatechnik

http://st.inf.tu-dresden.de/

teaching/most

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- 1) Problem of Tool Composition
- 2) Data definition languages
- 3) Query languages
- 4) Constraint languages
- 5) Reuse languages
- 6) Transformation and Restructuring languages
- 7) Behavior specification languages
- 8) Language families in several technical spaces
- 9) .. and all together now...



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# 14.1 Basic Techniques of Software Engineering, Language Families, and Tool Composition

### Q10: The House of a Technical Space

Model-Driven Software Development in Technical Spaces (MOST) **Technical Space Tool Engineering** Composition, Extension Mega- and Macromodels Tracing, Regeneration, Synchronization Technical Meta-Space modeling **Bridges** Model Management Composition, Mapping, Transformation Model Analysis Querying, Attribution, Analysis, Interpretation Metapyramid (Metahierarchy)

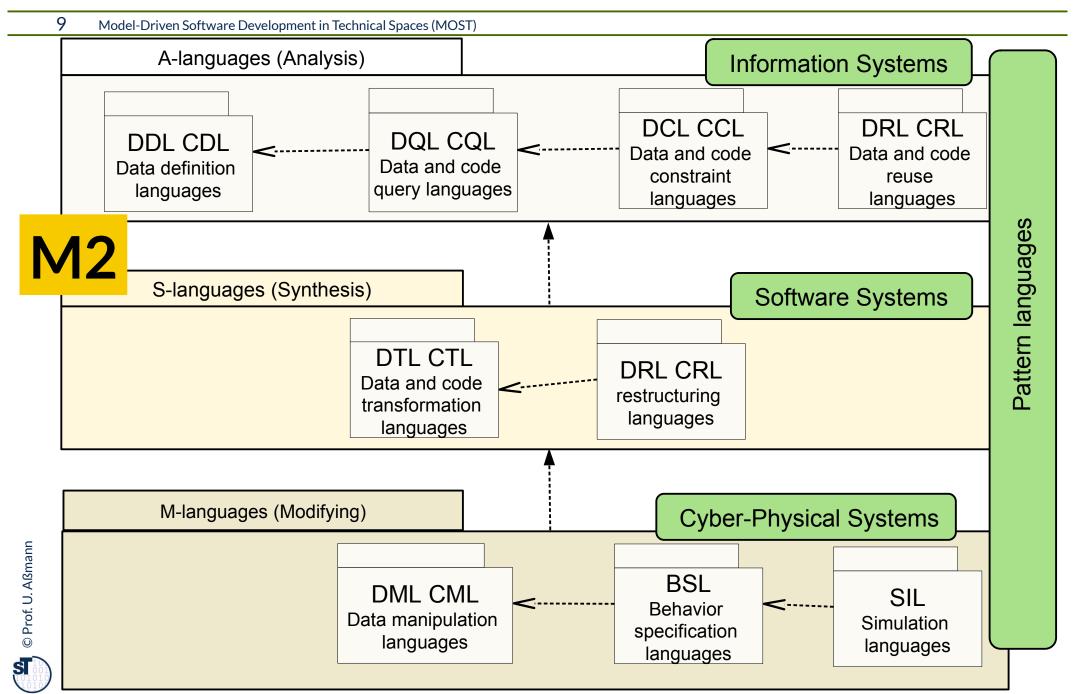


- M2 can systematically be divided into M2 layers (metamodel layer cake)
  - with metamodel packages in language families for:
  - Language engineering by composition
  - Tool construction by composition
  - Method and process engineering by composition of basic techniques
- Improves Tool engineering, Productivity of Process (Process Engineering), Test engineering, Simulation engineering
- Indirectly: Reliability of Software, Evolvability
- Different forms of Systems need different M2 layers:

Software Systems

Information Systems

## Basic Language Families (Layer Structure of M2, Metamodel Layer Cake)



#### Data and code modeling with definition languages (DDL, CDL)

Basic Language Families (Structure of M2)

- DDL form the basic packages of M2 to be imported by all other packages
- Ex: lifted metamodels, such as EBNF-Grammars, Relational Schema (RS), Entity-Relationship-Diagrams (ERD), UML-CD, SysML-Component diagrams
- In the metahierarchy, code covers M3-M0, because M0 is populated by objects of the dynamic semantics
  - Data does not have dynamic semantics, so it only covers M3-M1 (or M2-M0);
     however, when data is loaded as code, it changes its nature.
- Analysis languages (A-languages):

**Information Systems** 

- Queries with query languages (DQL, CQL)
- Consistency checking with data and code constraint languages (DCL, CCL) on wellformedness of data and code
- Reuse languages: Contract languages and composition languages
  - Architectural description languages (ADL)
  - Template-Sprachen (template languages, TL) → course CBSE



Software Systems

- **Declarative Transformation Languages (DTL, CTL)** 
  - Data flow diagrams (DFD)
  - Term- und graph rewrite systems
  - XML transformation languages
- **Restructuring Languages** (transformation languages retaining semantics, DRL, CRL)
  - Wide Spectrum Languages for refinement (broadband languages, **Breitbandsprachen**)

- Data and State **Manipulation Languages** (M-languages)
  - (non-declarative) Data manipulation languages (DML)
    - Workflow Languages, Petri Nets, Imperative languages
- Languages for **behavior specification language** (BSL)
  - Action-based state transition systems (finite automata and transducers)
  - Condition-Action-languages, Event-Condition-Action-languages (ECA)
- Simulation languages (Modelica, Simulink, OpenFoam) for discrete, continuous, and hybrd systems







Public domain https://cdn.pixabay.com/photo/2017/05/14/20/11/simulator-2312973\_960\_720.jpg

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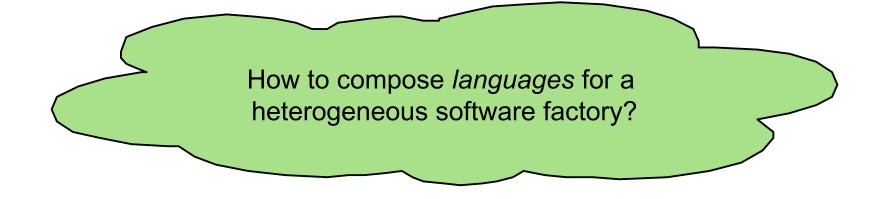
A software factory uses many base techniques and languages

Software Engineering of Heterogeneous Systems

- There is no homogeneous software construction
- Example: New electric car platform of VW and its design tool

A **software factory** is an environment to produce software and CPS product lines

- based on metamodeling, macromodels and pattern languages
- in one technical space or bridging several technical spaces





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## 14.2 Data Definition Languages (DDL) and Code Definition Languages (CDL)

The basic layer of M2 Usually lifted to M3 (i.e., self-descriptive)

All materials are shaped by a DDL or CDL



### Data Dictionaries (Data Catalogues) as Basis for all Tools and IDE

#### Model-Driven Software Development in Technical Spaces (MOST)

- A data dictionary (data schema) contains all types of data flowing through a system, including those stored in a repository (on M1)
  - Scope: local for an application, for several applications, for an entire company or even for a supply chain
  - A data dictionary is a special kind of model repository
  - If the data are models, it is called metamodel repository
- A homogeneous data dictionary is specified in a DDL
  - EBNF defines text languages (sets of text types)
  - Relational Schema (RS) defines relations and tabels
  - XML Schema (XSD) defines tree languages
  - ERD or UML-CD define graph languages
- A heterogeneous data dictionary is specified in several DDL
  - Usually, software factories maintain heterogeneous metamodel repositories

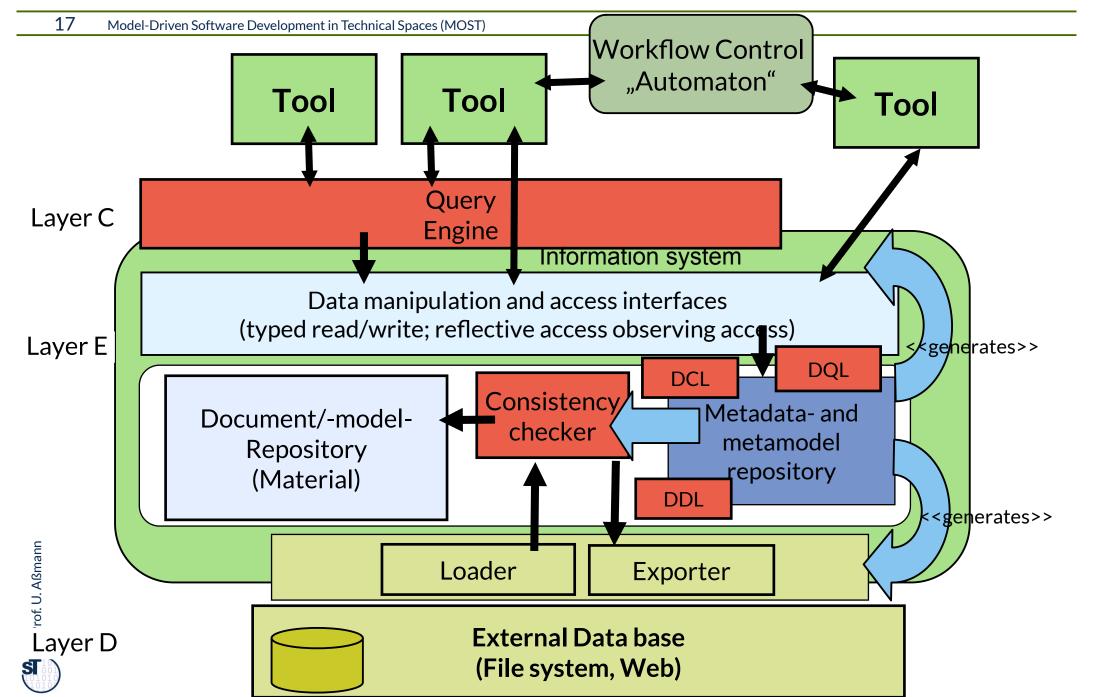


- An information system is a software system conducting data analysis about a repository
  - Data warehouses, business intelligence, data analytics

Information Systems are based on DDL

- A stream-based information system is a software system conducting data analysis on a set of data streams
- Every software tool, every IDE, every software factory relies on an information system
  - maintaining artefacts (data, programs, models, documents)
  - giving information about them
  - typed by the types in a data dictionary
- The data dictionary is described in a data definition language (DDL) or code definition language (CDL)
- The repository and the data streams are queried and analyzed by A-languages

## Q7: Standalone Tool Architecture with Data Sharing in a Metamodel-Driven Repository



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#### 14.3 Query Languages (QL)

DQL - Data Query Languages

CQL - Code Query Languages

All materials are queried by technical tools shaped by a DQL or CQL.



- Querying a tool's internal repository
  - Pattern matching of structural patterns
  - Joining information
  - Reachability queries
- Metrics : counting of patterns
- Analysis: Deeper knowledge (implicit knowledge)
  - Program and model analyses on value and type flow



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## 14.4 Constraint Languages (DCL,CCL) for Consistency Checking

All materials are constraint-checked by technical tools shaped by a DCL or CCL.



A model is well-formed (consistent), if it fulfils the context-sensitive constraints (integrity rules, consistency rules) of its metamodel.

A metamodel is wellformed, if it fulfils the context-sensitive constraints of its metametamodel.



A model repository (data dictionary) is wellformed, if all contained models fulfil its context-sensitive constraints.

A metamodel repository is wellformed, if it fulfils all its context-sensitive constraints.





A multimodel is wellformed, if it fulfils all its context-sensitive constraints. Then it is called a consistent multi- or macromodel.



### A **reuse language** is a (sub-)language) controlling the reuse of program or model elements (modularity).

Reuse Languages and Contract Languages for Modularity

#### **Examples:**

- Visibility languages define constructs for the visibility and reuse of model elements
- Contract languages check whether components, modules, classes, procedures and methods are applied correctly
- Interface definition languages describe types for interfaces in different languages, for heterogeneous software
  - see course CBSE
- Component model definition languages define reuse languages and contract languages [Johannes-PhD]



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#### 14.5 Data Transformation Languages (DTL)

Text, XML, Term, and Graph Rewriting see separate Chapter



- A DML (data manipulation language, Datenmanipulationssprachen) is used to transform data
- Declarative DTL (Datentransformationssprachen, DTL) consist of declarative rule systems transforming a repository
  - Term rewriting for trees, terms, link trees, and XML trees
  - Graph rewriting for graphs
- ► Imperative DML (general DML) know states and side effects.



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Restructuring Languages (DRL)

- Restructuring means to transform while to retain invariants.
- A restructuring language is a DTL giving guarantees about the transformed materials.
- A refactoring language restructures code and retains some of its invariants
- Languages for Refinement:
  - Refinement means that a transformed program implies the semantics of the original
  - A wide spectrum language transforms programs by refinement, generating more and more versions *implying* the requirements specification (the original)



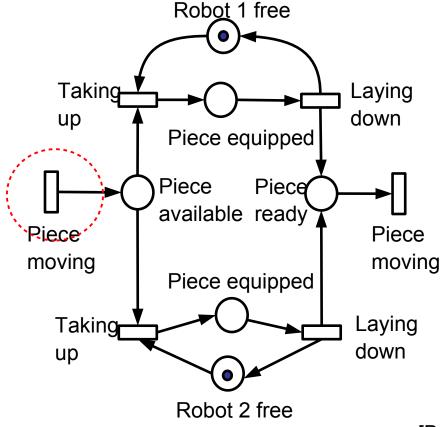
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### 14.6. Behavior Specification Languages (BSL)

All automata (workflow engines) in a TS execute workflows written in a BSL.



- State-oriented Behavior specification languages enable the specification of interpreters (operational dynamic semantics) and simulators (interpreters with a specific platform)
- Automata, Transducers,
   Statecharts → course
   Softwaretechnologie-I
- DFD, Petri-Nets and Workflow languages → course
   Softwaretechnologie-II
- Event-condition-action languages
   (ECA languages) → course
   Softwaretechnologie-II





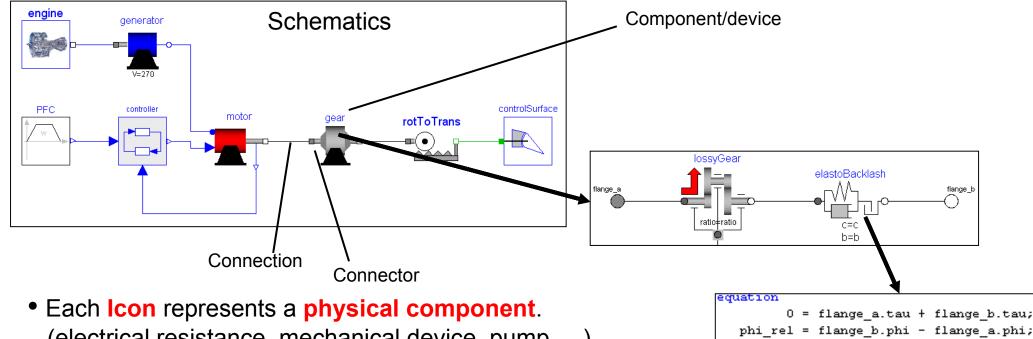
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### 14.6.1. Simulation Languages (SL)



#### Modelica Users View

29 Model-Driven Software Development in Technical Spaces (MOST) courtesy to Peter Fritzson



- (electrical resistance, mechanical device, pump, ...)
  - A connection line represents the actual physical coupling (wire, fluid flow, heat flow, ...)
  - A component consists of connected sub-components (= hierarchical structure) and/or is described by **equations**.
  - By symbolic algorithms, the high level Modelica description is transformed into a set of explicit differential equations:

$$0 = \mathbf{f}(\dot{\mathbf{x}}(t), \mathbf{x}(t), \mathbf{y}(t), t)$$

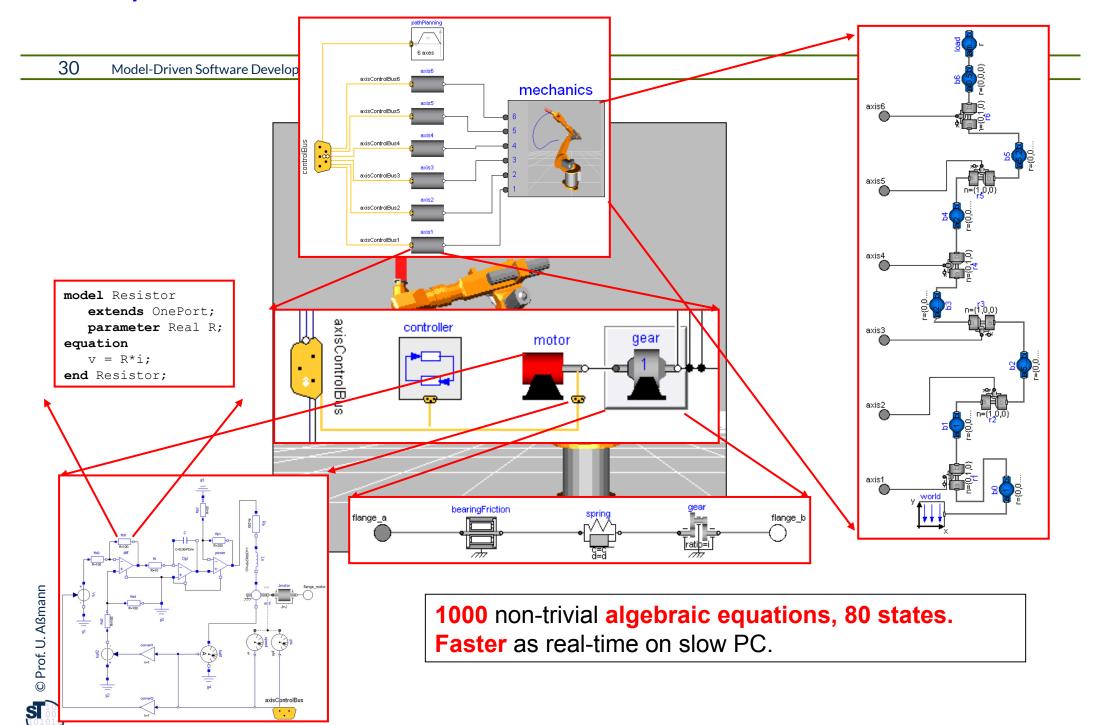
$$\dot{\mathbf{x}}(t) = \mathbf{f}(\mathbf{x}(t), t)$$

w rel = der(phi rel);

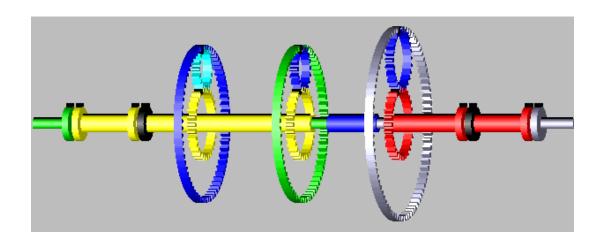
$$\mathbf{y}(t) = \mathbf{f}(\mathbf{x}(t), t)$$

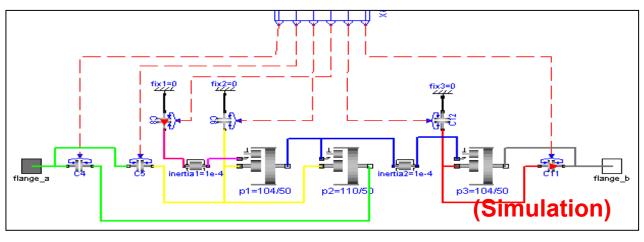


#### **Example: Industrial Robots** (from Modelica.Mechanics.MultiBody.Examples.Systems.RobotR3.fullRobot)



Electronic Control Unit (Hardware)





- + driver + engine
- + 1D vehicle dynamics



#### 14.7 Examples of Language Families on the M2 Layers

Every technical space has a language hierarchy on M2 with a similar, layered structure.

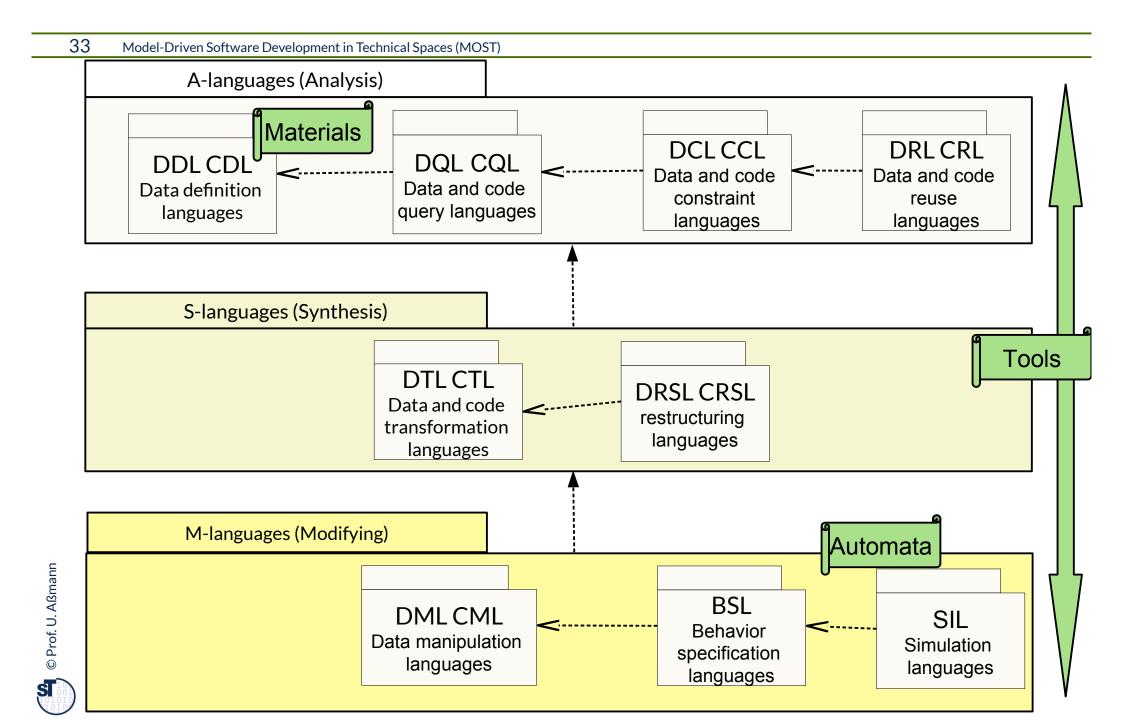
All tools have an underlying language family.

Every IDE has an underlying language family.

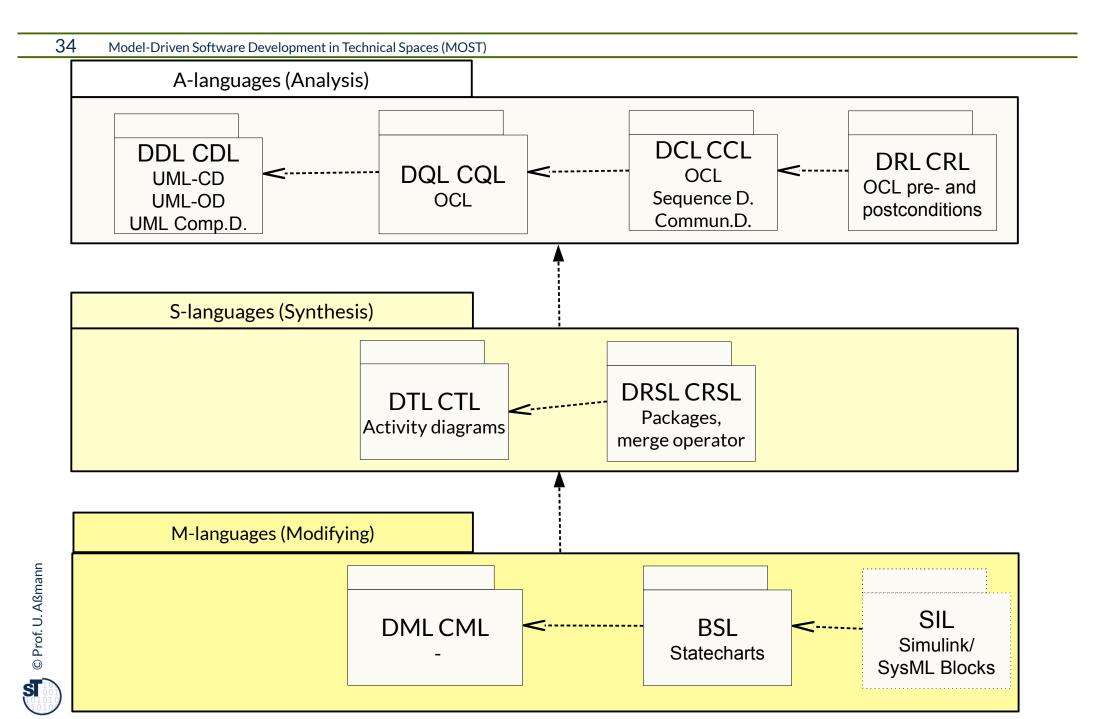
DRESDEN concept Exzellenz aus Wissenschaft und Kultur

Every software factory has several underlying language family.

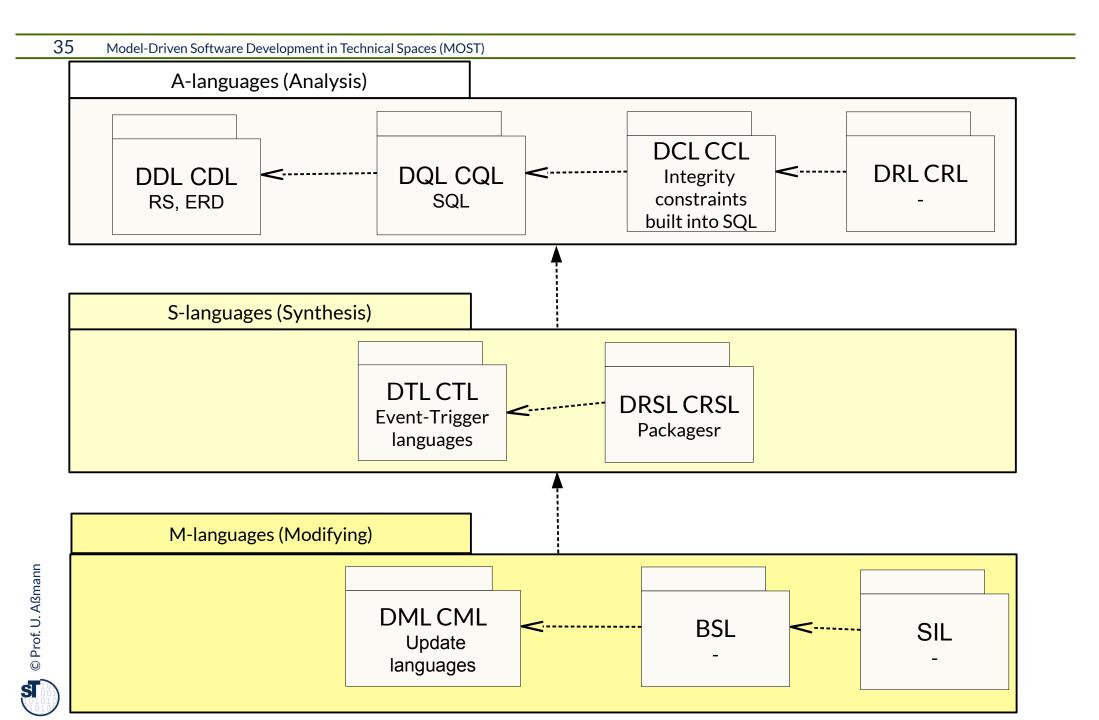
### Basic Language Families (Layer Structure of M2)



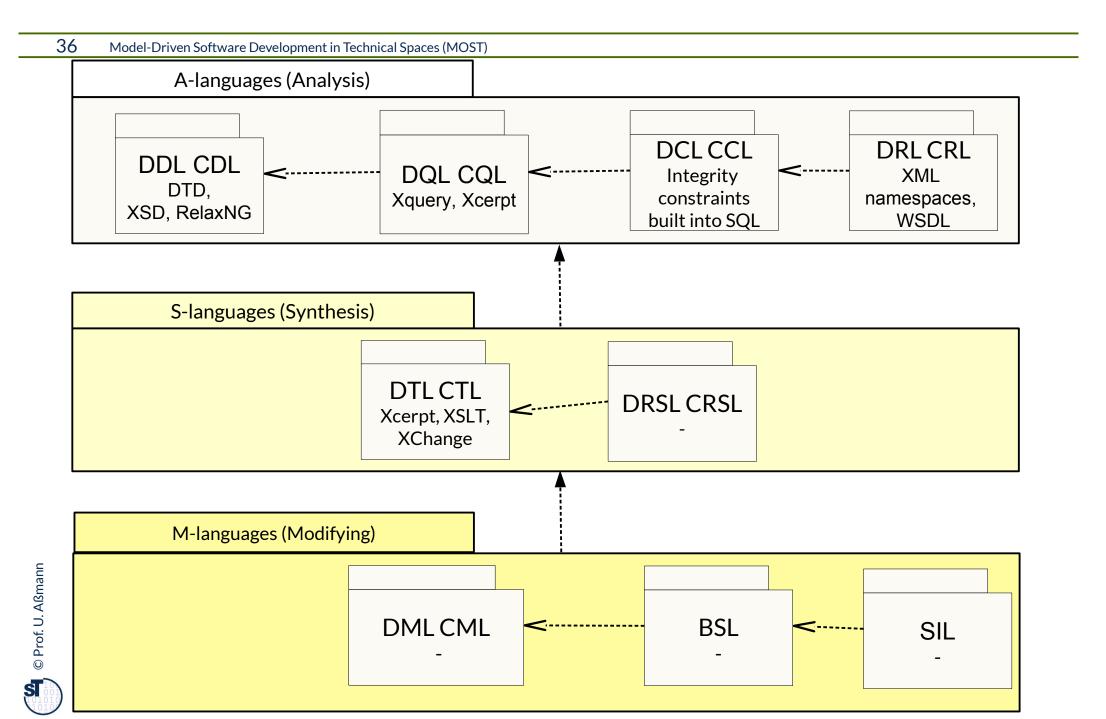
### UML Language Family in the ModelWare TS



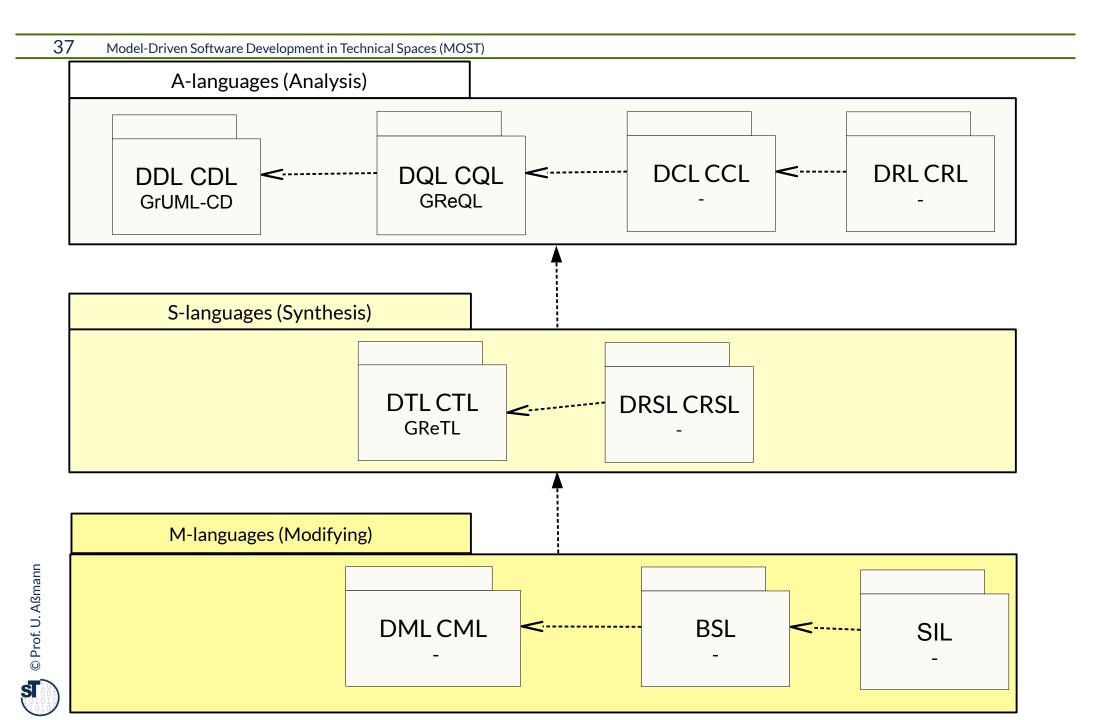
#### ERD/RS Language Family in the Relational TS



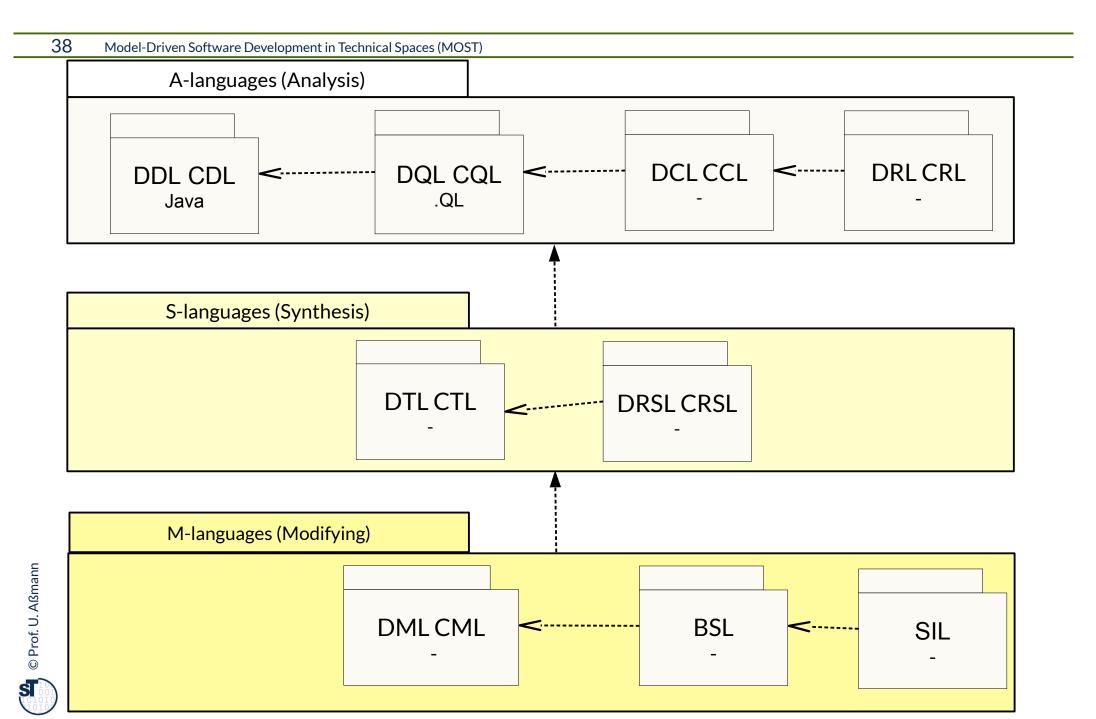
### XML Language Family in the Link Tree TS



### GrUML Language Family [Ebert, U Koblenz]



### .QL Language Family [Semmle, github]



### The Generic Tools of a Technical Space (TS)

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M3 metametamodel level

Metalanguage

Modelling concepts

M2 metamodel level

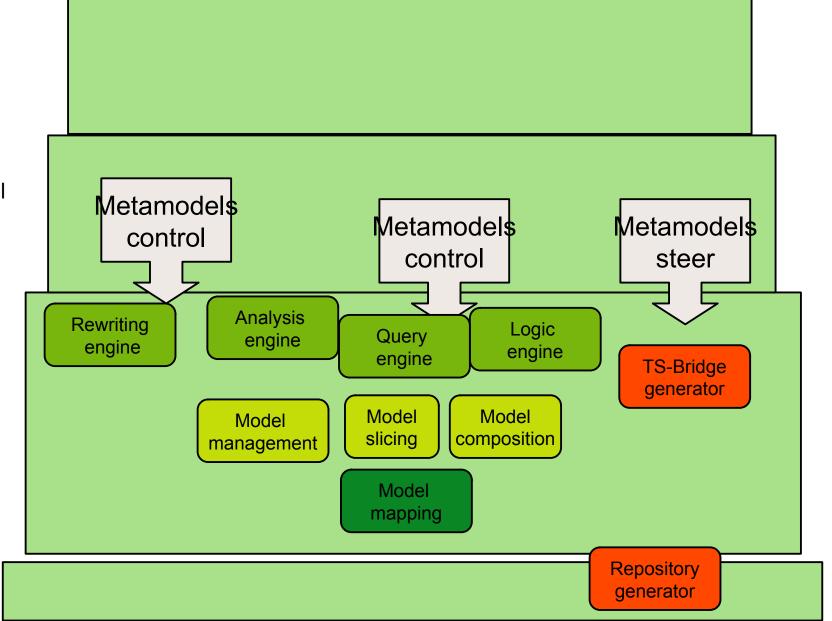
Metamodels

(languages)

M1 model level

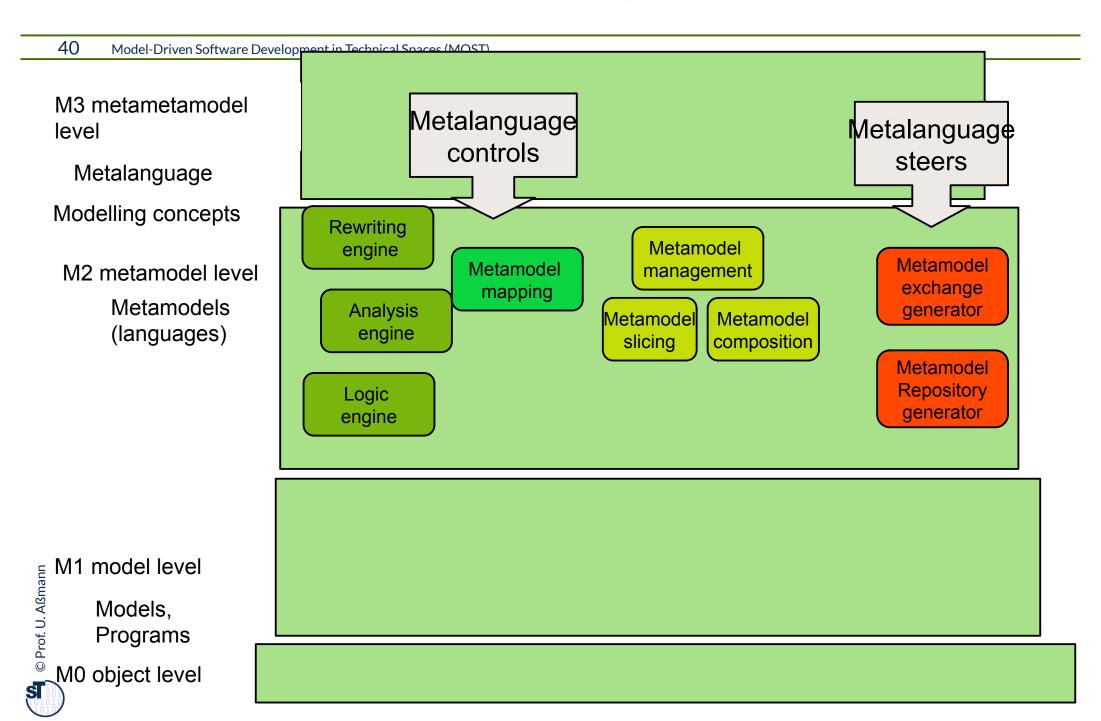
Models,

Programs

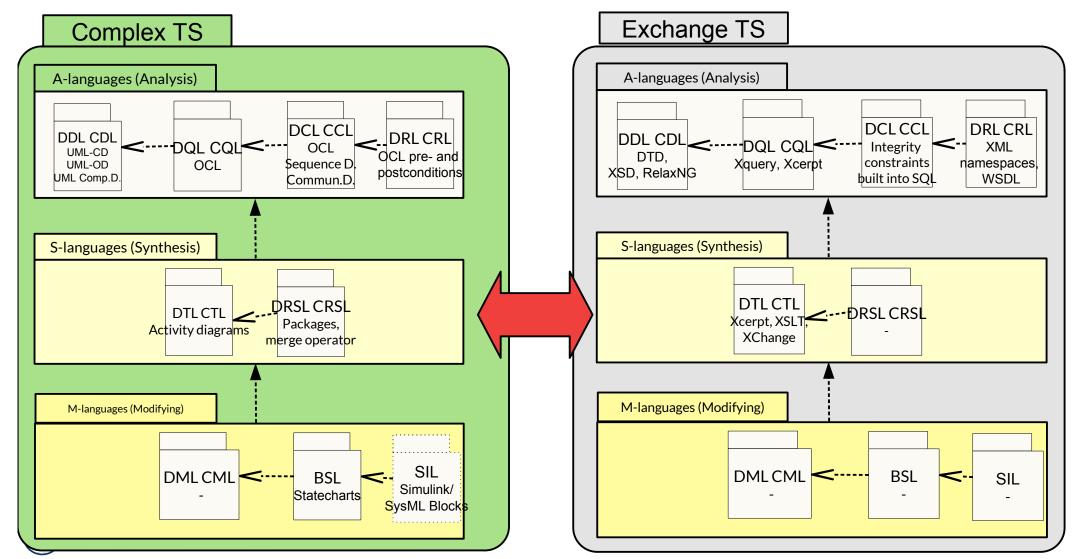


O object level

### The Generic Tools of a Technical Space (2)



- Complex technical spaces must be flattened to a textual exchange TS (here XML)
- Due to layering and packaging, language mappings are simpler





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14.8. ... and all together now...



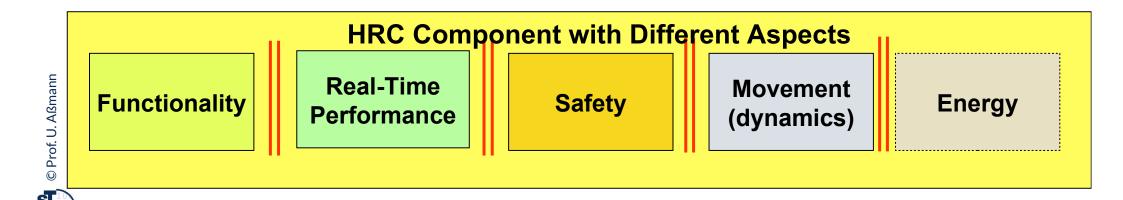
#### Example Megamodel:

## Composition of Contracts in the HRC (Heterogeneous Rich Components) MDSD Tool Chain for Complex Embedded Systems

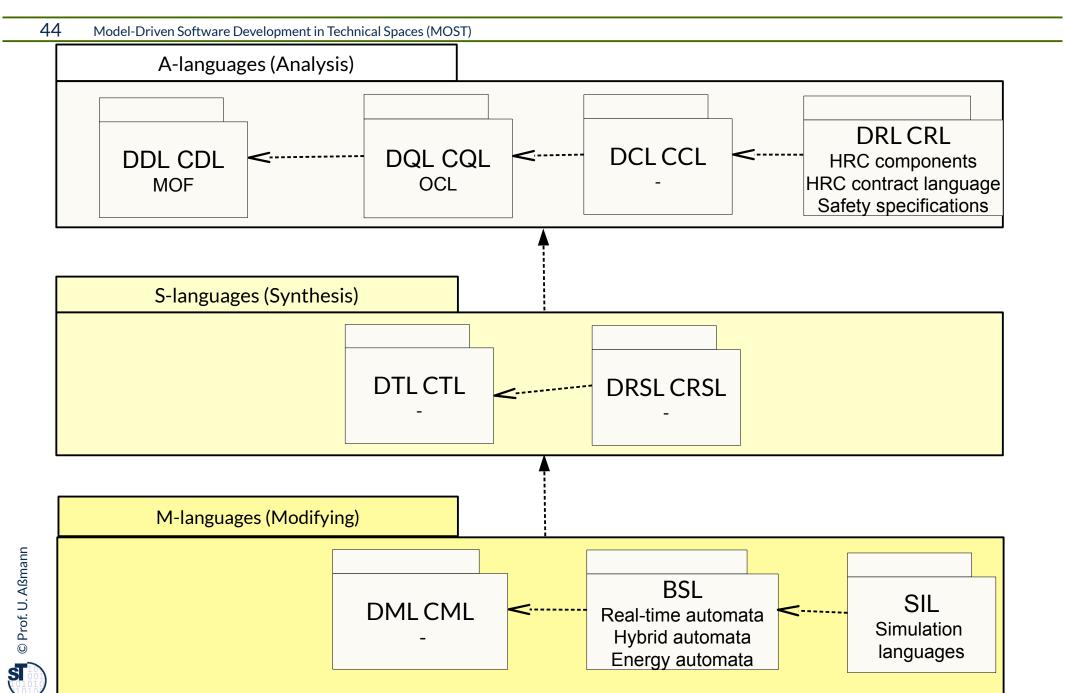
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[courtesy to Vered Gafni]

- Within a HRC component, contracts in different views can be synchronized (synchronized token-based modeling) [Damm]
  - The real-time assertions can be coupled with functional, real-time, safety, physical movement (dynamics), and energy view
  - Every contract has a different contract language
- Between different components, the contracts of a certain viewpoint can be composed and checked (viewpoint-specific modeling)



# Example Megamodel: HRC Language Family for Safety-Critical Embedded Software





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# 14.8.1. Technical Space Bridges and the Metamodel Layer Cake



# The multimodels managed by software factories combine different languages from several layers of M2 (**M2-Mix**)

Why is it Important to Know about the M2-Layers?

- ERD MOF XSD UML-CD
- Xquery XSLT SQL SPARQL
- OCL SpiderDiagrams OntologyLanguages
- ► Java C++ C#
- Petrinets DFD WorkflowNets BPMN

#### **Domain-specific languages always consist of an M2-Mix**

Methods also

#### How can we compose metamodels for tool composition?

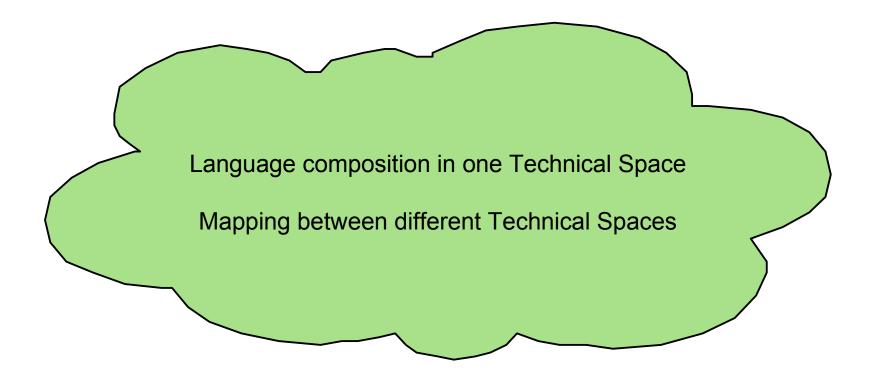
Vhy is it Important to Know about the M2-Structure?

- Language families can be arranged in M2 layers
  - Many languages on upper layers can be composed with languages on lower layers
- If everything is in one Technical Space, composition of tools relies on the composition of languages
  - For that we need Model Composition Systems (forthcoming, → course CBSE)
    - Example: UML-Package Merge-Operator

Language composition: Compose new language constructs from layers further down



If we have to treat several Technical Spaces, Bridges between TS have to be built





The End - Exam Questions

- ▶ Where would you position a query tool on M1 in the tools layer or in the materials layer? Does the tool's metamodel in its query language belong then to the tools metamodel layer of M2 or to the materials metamodel layer?
- Why can we compose different DQL with a given DDL?
- How is it possible to apply a graph query language on XML trees?
- Why is UML such a complex language?
- A MDSD tool chain such as the HRC IDE for embedded systems works with many languages in different technical spaces. Explain some ingredients of such a complex IDE.